

# Ludicrously Large-Scale Stochastic Energy Optimization in SMS++

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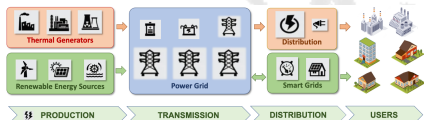
... & many others

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The second HEXAGON workshop on power grids

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# Outline

- 1 A View on (some) Energy Optimization Models
- 2 How on Earth do you solve THAT?!?
- 3 All the above in SMS++-speak
- 4 How on Earth do you model THAT?!?
- 5 Some Results
- 6 Conclusions

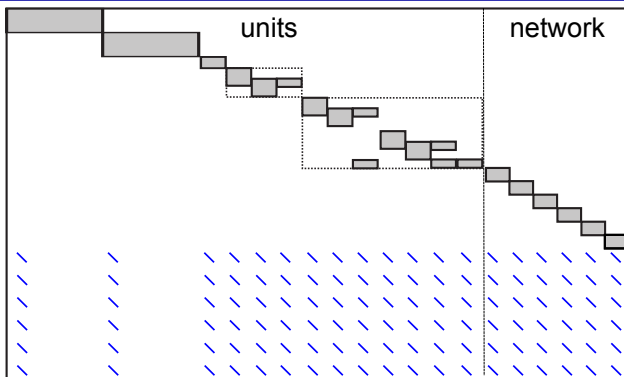
# Energy Optimization bottom-up: Unit Commitment

- I don't need to convince you that energy optimization is important, but **which** of the many energy optimization problems??
- Operational level = Unit Commitment<sup>1</sup>: schedule **generating units** over **time horizon** (hours / 15m in day / week) to satisfy (forecasted) **demand**
- Different types of production units, different constraints:
  - Thermal (comprised nuclear): min / max production, min up / down time, ramp rates on production increase / decrease, start-up cost depending on previous downtime, others (modulation, ...)
  - Hydro (valleys): min / max production, min / max reservoir volume, time delay to get to the downstream reservoir, others (pumping, ...)
  - **Non programmable** (ROR hydro) **intermittent** units (solar / wind, ...)
  - Fancy things (small-scale storage, demand response, smart grids, ...)
- Plus the **interconnection network** (AC / DC, transmission / distribution, OTS, ...) and **reliability** (primary / secondary reserve,  $n - 1$  units, ...)

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<sup>1</sup> van Ackooij, Danti Lopez, F., Lacalandra, Tahanan "Large-scale Unit Commitment Under Uncertainty [...]" AOR 2018

# Many Different Structures Already



- Many different structures: thermal units<sup>2</sup>, hydro units<sup>3</sup>, Energy Communities<sup>4</sup>, stochastic<sup>5</sup>, AC-OPF<sup>6</sup>, OTS<sup>7</sup>, ...

<sup>2</sup>Bacci, F., Gentile, Tavlaridis-Gyparakis "New MINLP Formulations for the Unit Commitment Problem [...]" *OR* 2024

<sup>3</sup>van Ackooij et. al. "Shortest path problem variants for the hydro unit commitment problem" *Elec. Notes Disc. Math.* 2018

<sup>4</sup>Fioriti, F., Poli "Optimal Sizing of Energy Communities with Fair Revenue Sharing [...]" *Applied Energy* 2021

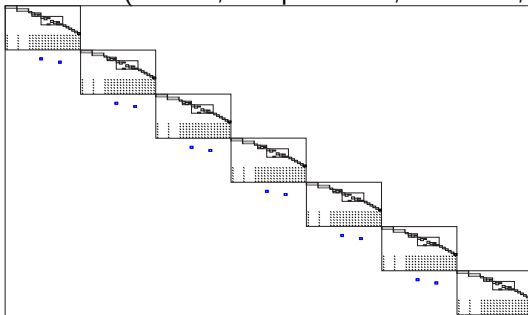
<sup>5</sup>Scuzziato, Finardi, F. "Comparing Spatial and Scenario Decomposition for Stochastic [...]" *IEEE Trans. Sust. En.* 2018

<sup>6</sup>Bienstock, Escobar, Gentile, Liberti "[...] formulations for the alternating current optimal power flow" *Ann. O.R.*, 2022

<sup>7</sup>Numan et. al. "The role of optimal transmission switching in enhancing grid flexibility: A review" *IEEE Access*, 2023

# The tactical level: Seasonal Storage Valuation

- Mid-term (1y) cost-optimal management of water levels in reservoirs considering **uncertainties** (inflows, temperatures, demands, ...)



- **Very large size**, **nested structure** (one UC per stage)
- Perfect structure for Stochastic Dual **Dynamic Programming**<sup>8,9</sup>
- SDDP needs **dual variables**, but **Lagrangian dual convexifies**<sup>10,11</sup>

<sup>8</sup> Pereira, Pinto "Multi-stage stochastic optimization applied to energy planning" *Math. Prog.*, 1991

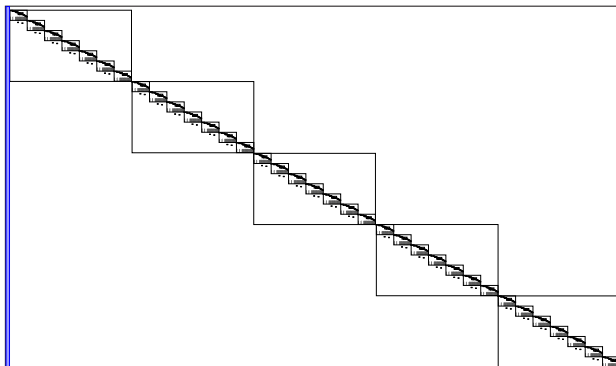
<sup>9</sup> van-Ackooij, Warin "On conditional cuts for Stochastic Dual Dynamic Programming" *EURO J. on Comp. Opt.*, 2020

<sup>10</sup> Lemaréchal, Renaud "A geometric study of duality gaps, with applications" *Math. Prog.* 2001

<sup>11</sup> F. "About Lagrangian Methods in Integer Optimization" *Annals of O.R.*, 2005

# Energy System Investment

- Investment on generating units / transmission lines
- Using **stochastic independent representative years** to evaluate system cost



- **Very few** investment variables, can be taken **continuous**, **identical copies**
- Would be **perfect for Benders'**-like<sup>12,13</sup>, **if given dual information**

<sup>12</sup> Geoffrion "Generalized Benders Decomposition" *JOTA*, 1972

<sup>13</sup> van Ackooij, F., de Oliveira "Inexact Stabilized Benders' Decomposition Approaches [...]" *COAP*, 2016

# Mathematics of convex investment problems

- Set  $N$  of generation / distribution units,  $\kappa_i$  identical copies of each  $i \in N$
- For  $\kappa = [\kappa_i]_{i \in N}$ , investment cost  $F(\kappa)$  (“easy”) and operational cost

$$\begin{aligned}
 O(\kappa) = \min \quad & \sum_{i \in N} \sum_{j=1}^{\kappa_i} c_i(x_{i,j}) \\
 \text{s.t.} \quad & x_{i,j} \in X_i \quad j = 1, \dots, \kappa_i, \quad i \in N \quad (1) \\
 & \sum_{i \in N} \sum_{j=1}^{\kappa_i} A_i x_{i,j} \geq d
 \end{aligned}$$

- Everything convex  $\implies$  all  $i \in N$  produce identically at optimality  $\implies$

$$\begin{aligned}
 O(\kappa) = \min \quad & \sum_{i \in N} \kappa_i c_i(x_i) \\
 \text{s.t.} \quad & x_i \in X_i \quad i \in N \quad (2) \\
 & \sum_{i \in N} \kappa_i A_i x_i \geq d
 \end{aligned}$$

- Extends to stochastic setting ( $S$  = scenarios,  $\mathcal{N}$  = nonanticipativity)

$$\begin{aligned}
 O(\kappa) = \min \quad & \sum_{i \in N} \kappa_i \sum_{s \in S} \pi^s c_i^s(x_i^s) \\
 \text{s.t.} \quad & x_i^s \in X_i^s \quad i \in N, \quad s \in S \quad (3) \\
 & \sum_{i \in N} \kappa_i \sum_{s \in S} A_i^s x_i^s \geq d, \quad x \in \mathcal{N}
 \end{aligned}$$

# A triply clever trick

- Investment problem  $\min\{F(\kappa) + O(\kappa) : \kappa \in K\}$ : extremely hard as even (2) / (3) hard ((1) harder), since convexity assumption untrue
- Lagrangian relaxation triply clever:
$$\phi(\lambda, \kappa) = \lambda d + \sum_{i \in N} \kappa_i \min\{c_i(x_i) - \lambda A_i x_i : x_i \in X_i\}$$
  - decomposes into (many, easier, smaller) independent subproblems
  - automatically convexifies  $c$  and  $X$ <sup>11</sup>
  - $\phi(\lambda, \kappa)$  is concave in  $\lambda$  and affine in  $\kappa$
- Convexified version:  $\underline{Q}(\kappa) = \max\{\phi(\lambda, \kappa) : \lambda \geq 0\} = \phi(\lambda^*(\kappa), \kappa)$
- Convexified Investment Problem:  $\min\{F(\kappa) + \underline{Q}(\kappa) : \kappa \in K\}$  possibly the best trade-off between computability and accuracy
- Crucial:  $[c_i(x_i^*(\lambda^*(\kappa))) - \lambda^*(\kappa) A_i x_i^*(\lambda^*(\kappa))]_{i \in N} \in \partial \underline{Q}(\kappa)$ <sup>14</sup>  
 $\implies$  can use bundle methods<sup>??</sup> or stabilised Benders' ones<sup>15</sup>

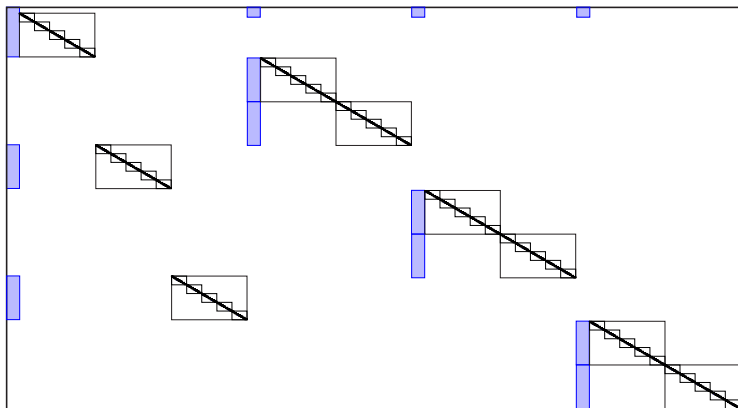
<sup>14</sup> van Ackooij, Oudjane "On supply and network investment in power systems" 4OR, 2024

<sup>15</sup> van Ackooij, F., de Oliveira "Inexact Stabilized Benders' Decomposition Approaches [...]" COAP, 2016



# Strategic Energy System Investment (“the Big Kahuna”)

- Long-term (30y) optimal (cost, pollution, CO<sub>2</sub> emissions, ...) planning of production/transmission investments considering multi-level **uncertainties scenarios** (technology, economy, politics, ...)



- Many scenarios, huge size, multiple nested **structure**  $\Rightarrow$  multiple nested Benders' or Lagrangian decomposition and/or SDDP??

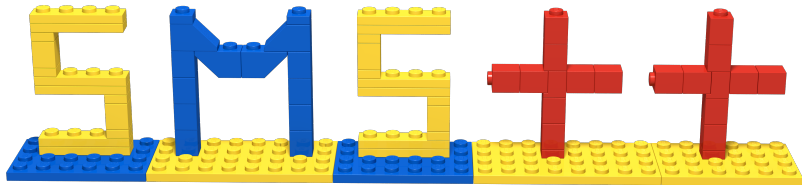
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A HUGE LOT OF  
ELBOW GREASE,  
BLODISHED AND TEARS

or

Quite a lot of elbow grease and



<https://gitlab.com/smspp/smspp-project>

“For algorithm developers, from algorithm developers”

- Open source (LGPL3)
- 1 “core” repo, 1 “umbrella” repo, 12+ problem and/or algorithmic-specific repos (public, more in development), tests & tools
- Extensive Doxygen documentation <https://smspp.gitlab.io>
- But no real user manual as yet (except myself)

# What SMS++ is

- A core set of C++-20 classes implementing a **modelling system** that:
  - explicitly supports the notion of **Block  $\equiv$  nested structure**
  - separately provides “semantic” information from “syntactic” details (list of constraints/variables  $\equiv$  **one specific** formulation among many)
  - allows exploiting **specialised Solver** on Block with specific structure
  - manages **any dynamic change in the Block** beyond “just” generation of constraints/variables
  - supports **reformulation/restriction/relaxation** of Block
  - has built-in **parallel processing capabilities**
  - **should** be able to deal with almost anything (bilevel, PDE, ...)
- An **hopefully** growing set of specialized Block and Solver
- **In perspective** an **ecosystem fostering collaboration and code sharing**: a community-building effort as much as a (suite of) software product(s)

# What SMS++ is not

- **An algebraic modelling language:** Block are C++ code (although it provides some modelling-language-like functionalities)
- **For the faint of heart:** primarily written for algorithmic experts (although users may benefit from having many pre-defined Block)
- **Stable:** only version 0.5.2, lots of further development ahead, significant changes in (parts) of interfaces actually expected (although current Block / Solver very thoroughly tested)
- **Interfaced with many existing solvers:** Cplex, SCIP, MFCClass, StOpt (but the list recently grew with Guorbi, HiGHS and LEMON)
- **Ripe with native structure-exploiting solvers:** LagrangianDualSolver and SDDPSolver for now (although the list should hopefully grow)

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# It starts deceptively simple

**ThermalUnitBlock : Block**

$$\min \sum_{i \in P} c^i(\mathbf{p}^i, \mathbf{u}^i) = \sum_{i \in P} \left( c^i(\mathbf{u}^i) + \sum_{t \in \mathcal{T}} c_t^i(p_t^i) \right)$$

$$\bar{p}_{\min}^i u_t^i \leq p_t^i \leq \bar{p}_{\max}^i u_t^i \quad t \in \mathcal{T}$$

$$p_t^i \leq p_{t-1}^i + u_{t-1}^i \Delta_+^i + (1 - u_{t-1}^i) \bar{I}^i \quad t \in \mathcal{T}$$

$$p_{t-1}^i \leq p_t^i + u_t^i \Delta_-^i + (1 - u_t^i) \bar{u}^i \quad t \in \mathcal{T}$$

$$u_t^i \geq u_r^i - u_{r-1}^i \quad t \in \mathcal{T}, \quad r \in [t - \tau_+^i, t - 1]$$

$$u_t^i \geq 1 - u_{r-1}^i - u_r^i \quad t \in \mathcal{T}, \quad r \in [t - \tau_-^i, t - 1]$$

$$u_t^i \in \{0, 1\} \quad t \in \mathcal{T}$$

T   a[] b[] c[]   Dp[]

p\_min[] p\_max[] Dm[]

- For a man with a hammer everything is a nail

# It starts deceptively simple

**ThermalUnitBlock : Block**

$$\min \sum_{i \in P} c^i(\mathbf{p}^i, \mathbf{u}^i) = \sum_{i \in P} \left( c^i(\mathbf{u}^i) + \sum_{t \in \mathcal{T}} c_t^i(p_t^i) \right)$$

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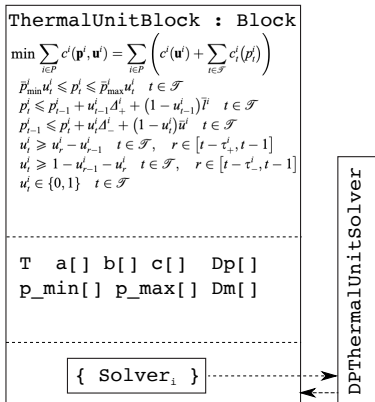
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T   a[]   b[]   c[]   Dp[]

p\_min[]   p\_max[]   Dm[]

- For a man with a solver everything is a Block (call me blockhead 🤖)
- **Block** = abstract class representing the general concept of  
“(fragment of) mathematical model with a well-understood semantic”
- Each **:Block** a model with **specific structure**: ThermalUnitBlock :  
Block = a single-(thermal)-unit commitment problem

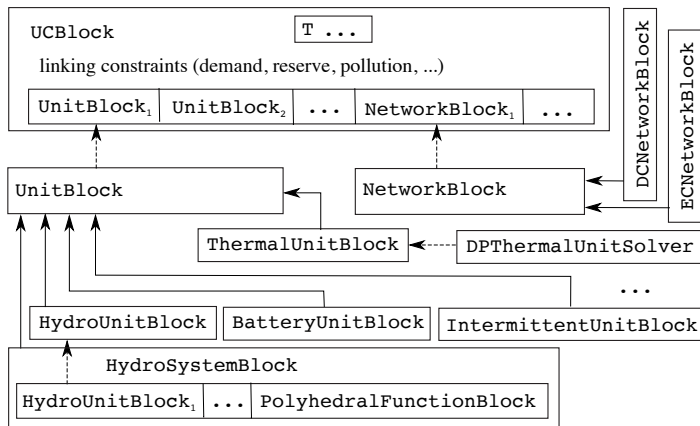
# A Block $\exists (\approx)$ because a (specialised) Solver $\exists$



- Any number of Solver can be attached to a Block
- Any specific :Block (e.g., ThermalUnitBlock) can have specialised  $\Rightarrow$  fast :Solver (e.g., DPThermalUnitSolver<sup>16</sup>)
- Can be wrapper classes to efficient existing (C++) libraries

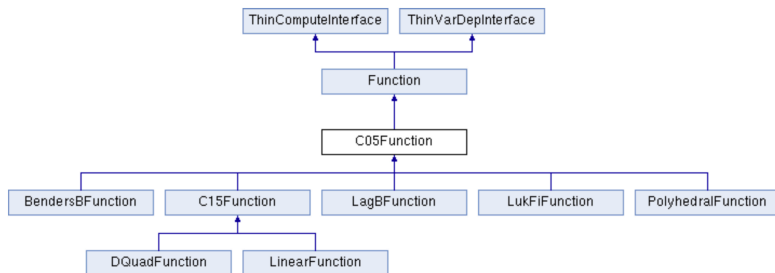
<sup>16</sup>F., Gentile "Solving Nonlinear Single-Unit Commitment Problems with Ramping Constraints" *Op. Res.*, 2006

# A Block is (almost) always just a (small) part



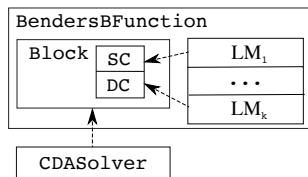
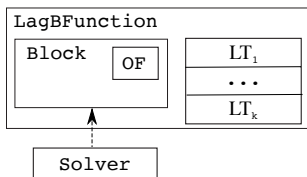
- A Block can have **any # of sub-Block, recursively** (Block \*); e.g.,  
UCBlock : Block has  $k$  :UnitBlock and  $T$  :NetworkBlock **recursively**
- **Problem data split between them** (energy constraints only in UCBLOCK)

# Another necessary step: Function



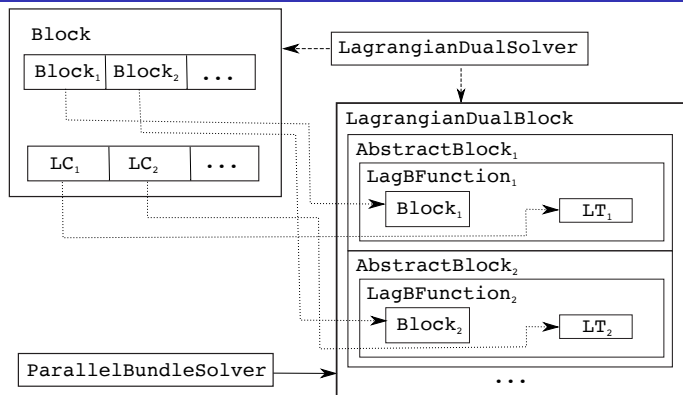
- Real-valued Function of a set of [Col]Variable (a single  $\mathbb{R}$  /  $\mathbb{Z}$ )
- Must be compute()-d w.r.t. the current value of the [Col]Variable, **possibly a costly operation** (:ThinComputeInterface)
- C05Function / C15Function have (**not necessarily continuous**)  
1<sup>st</sup> / 2<sup>nd</sup> order information (vertical / diagonal linearizations)
- **Local / global pools** of linearizations
- “Easy” Function (linear, quadratic, polyhedral, ...) with no overhead

# LagBFunction & BendersBFunction



- **LagBFunction**  $\equiv$  dual function  $\varphi(\lambda) = \min\{f(x) + (\lambda LT)x : x \in X\}$   
for (almost) any Block ( $B$ )  $\min\{f(x) : x \in X\}$
- **BendersBFunction**  $\equiv$  value function  
 $v(y) = \min\{f(x) : g(x) \leq LMy : x \in X\}$   
for (almost) any Block ( $B$ )  $\min\{f(x) : g(x) \leq 0, x \in X\}$
- Both are `:Block` and `:C05Function`, with ( $B$ ) being the only sub-Block
- Use generic `[CDA]Solver` to compute() ( $\approx$  just call its `compute()`)
- Store pools of primal / dual Solution corresponding to linearizations
- Any change in ( $B$ ) is mapped in changes of F-values / the pools

# All this $\mapsto$ LagrangianDualSolver



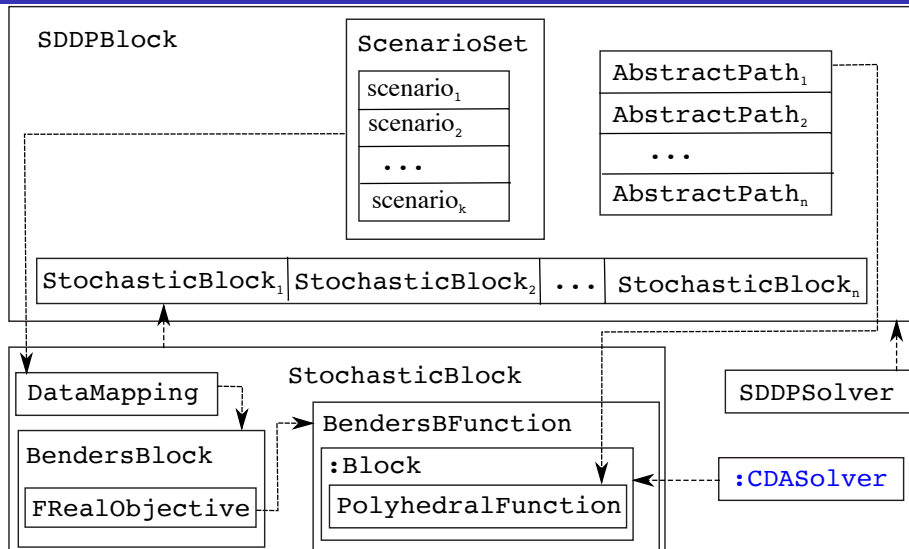
- Forms (hidden) LagrangianDualBlock, attaches parallel<sup>17</sup> Solver
- Provides primal (convexified  $\equiv$  “better”<sup>10,11</sup>) and dual solutions
- Good foundations for heuristic approaches<sup>18,19</sup> & the next steps

<sup>17</sup> Cappanera, F. “[...] Parallelization of [...] Algorithm for Multi-Commodity Flow Problems” *INFORMS JoC*, 2003

<sup>18</sup> Borghetti, F., Lacalandra, Nucci “Lagrangian [...] for Hydrothermal Unit Commitment”, *IEEE Trans. Power Sys.* 2003

<sup>19</sup> Scuzziato, Finardi, F. “Solving Stochastic [...] Unit Commitment with [...] Lagrangian Solutions” *IJEPES*, 2021

# SDDPBlock, StochasticBlock and their Solver

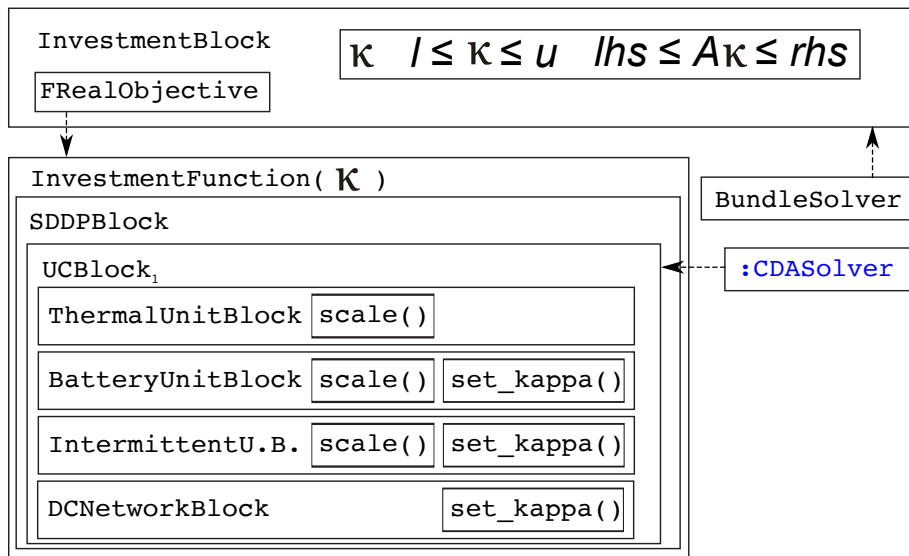


- SDDPSolver: wrapper for  $\text{StOpt}^{20}$  + SDDPGreedySolver (simulator)

<sup>20</sup> <https://gitlab.com/stochastic-control/StOpt>

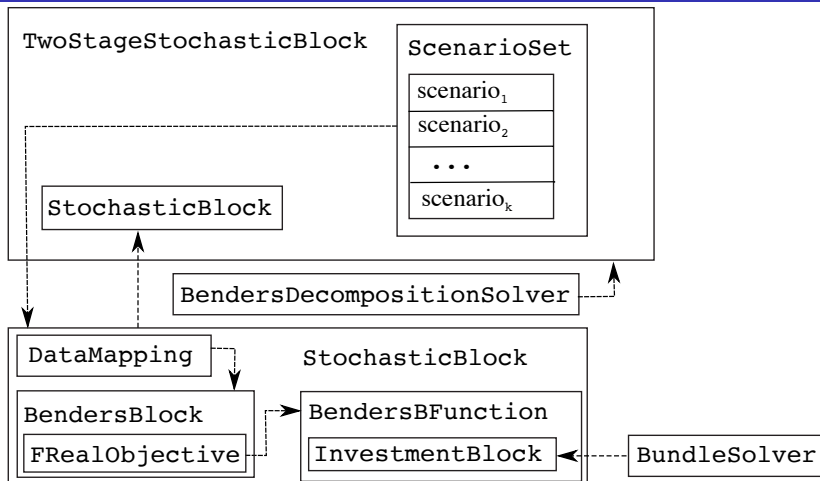


# InvestmentBlock



- Scaling a `:Block` a general concept, may be upcasted to base `Block`

# Strategic Investment Problem in SMS++-speak



- Not all here yet, TwoStageStochasticBlock still under active development, BendersDecompositionSolver yet to come
- Clearly extremely challenging problem, need all the help we can get

# SMS++ support to (coarse-grained) parallel computations

- Block can be (write) lock()-ed to ensure atomic changes
- lock()-ing a Block automatically lock()s all inner Block (recursively)
- Analogously for read\_lock(), any # of concurrent reads
- lock() (but not read\_lock()) sets an **owner** and records its `std::thread::id`; other lock() from the same thread fail (`std::mutex` would not work there)
- **Write starvation not handled yet**
- Solver's `compute()` must be thread-safe (`std::recursive_mutex`)
- Solver/ThinComputeInterface can be “lent ID” (solving a sub-Block)
- Solver's `list<Modification>` under an “active guard” (`std::atomic`)
- General **State** of Solver for **checkpointing** (and reoptimization)
- New **Change** concept: `Modification + data`, automatic **undo\_Change**, can be **de/serialize-d on netCDF file as everything**  $\implies$  **message-passing distributed Solver** available **one day** (soon-ish?)

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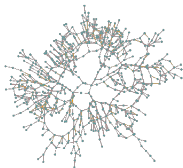
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QUITE SOME  
ELBOW GREASE AND  
netCDF FILES MANGLING

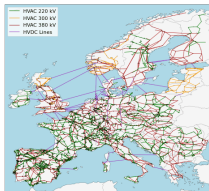
or

Some elbow grease and

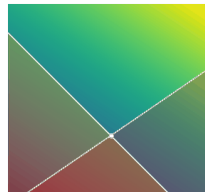
**PyPSA**



**PyPSA-Eur**



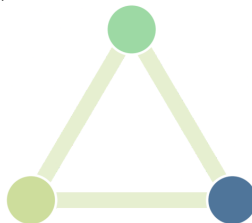
**Linopy**



<https://pypsa.org>

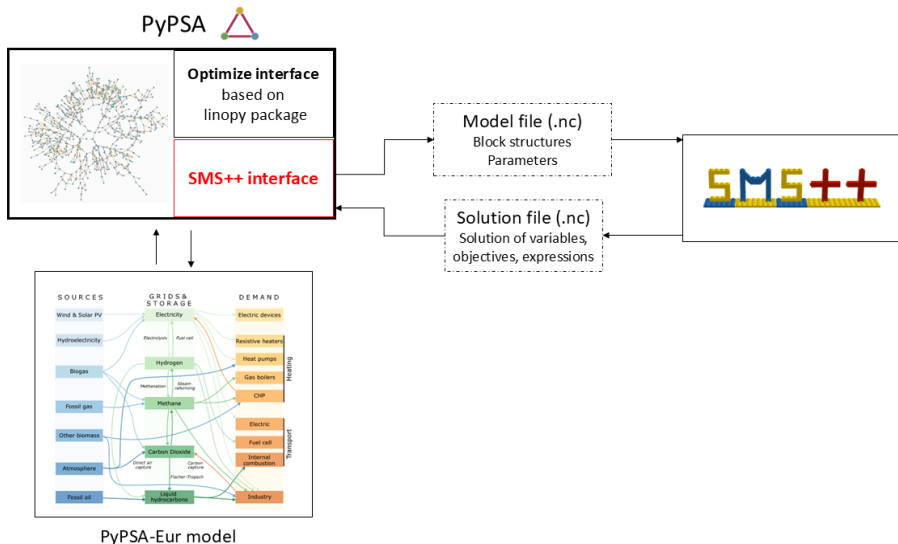
+

**RESILIENT**



<https://resilient-project.github.io>

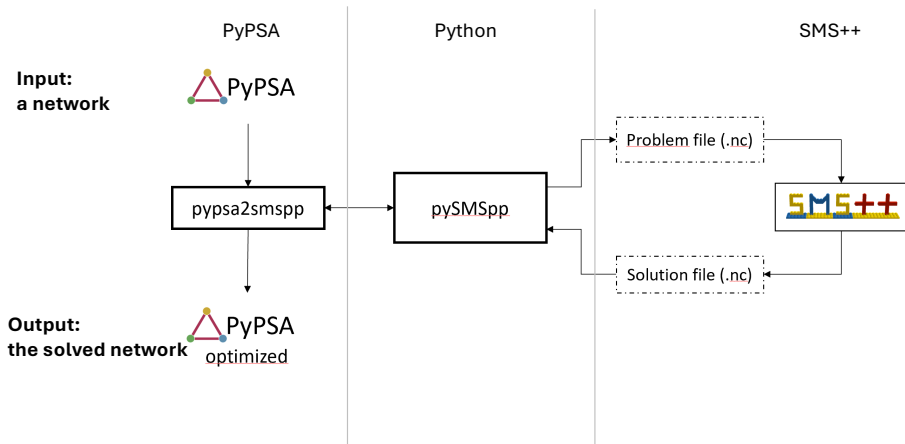
# What the project wants to do



- Modelling prowess of PyPSA + solution prowess of SMS++



# A bit more in details

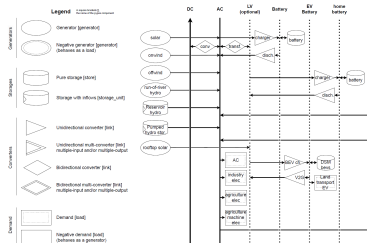


- Requires careful mapping of PyPSA network  $\mapsto$  SMS++:Block
- Especially important for freshly developed PyPSA stochastic extension

# A glimpse of the mapping

Equation	Symbol	Generator	Link	Line	Storage unit	Store	Condition	Example
Size bound	SB	X	X	X	X	X		$G_{i,r} \leq G_{i,r} \leq G_{i,r}$
Modularity	MD	X	X	X	X	X		$G_{i,r} = G_{i,r}^{max} n_{i,r}$
Power bound	PB	X	X	X	X	X		$\underline{g}_{i,r,t} G_{i,r} \leq g_{i,r,t} \leq \bar{g}_{i,r,t} G_{i,r}$
Power unit commitment	$PB_{UC}$	X	X				committable	$\delta_{i,r,t} \underline{g}_{i,r,t} G_{i,r} \leq g_{i,r,t} \leq \delta_{i,r,t} \bar{g}_{i,r,t} G_{i,r}$
Minimum time	MT	X	X					$\sum_{t=t-1}^{t+T_{min,up}} \delta_{k,t} \geq T_{min,up} (\delta_{k,t} - \delta_{k,t-1})$
Total energy produced	PSUM	X	X					$E_{i,r,t}^{max} \leq \sum_{t=t-1}^{t+T_{min,up}} w_i^t g_{i,r,t} \leq E_{i,r,t}^{max}$
Start up/shut down cost	SC	X	X					$suc_{k,t} \geq suc_k (\delta_{k,t} - \delta_{k,t-1})$
Rump up/down	RUD	X	X					$(g_{i,r,t} - g_{i,r,t-1}) \leq r u_{i,r} G_{i,r}$
Kirchhof's law	KL			X				$\sum_i G_{i,r,t} p_{i,t} = 0$
Line losses	LL			X				$p_{i,t}^{loss} = \alpha_i + \beta_i p_{i,t}$
Energy storage level	ESL				X	X		$e_{i,s,t} = e_{i,s,t-1} + w_i^s h_{i,s,t}$
Energy storage bound	ESB				X	X		$0 < e_{i,s,t} < E_{i,s,t}^{max}$
Initial energy level	$IEL_S$				X	X		$e_{i,s,0} = e_{i,s,init}$
Cyclic energy level	$IEL_{CS}$				X	X	cyclic_state_of_charge	$e_{i,s,0} = e_{i,s,T}$

A	B	C	D	E
Technology name	Category	Physical compone	Option	Carrier
co2 atmosphere	co2	N		co2
Co2 storage	co2	Y		co2 stored
Sequestration link	co2	N		co2 sequestered
Sequestration store (e.g. underground)	co2	Y/N		co2 sequestered
CO2 vent co2 from storages	co2	?	co2_vent	co2 vent
CO2 pipelines	co2	Y	co2_network	CO2 pipeline
Allam (gas) cycle	electricity	Y	allam	allam
Direct Air Capture	co2	Y	dac	dac
Conventional generators	electricity	Y	conventional_generation	electricity
Haber-Bosch process	ammonia	Y	ammonia	Haber-Bosch
Ammonia cracker	ammonia	Y	ammonia	ammonia cracker
Ammonia storage	ammonia	Y	ammonia	ammonia store
Electricity distribution	electricity	Y	electricity_distribution_grid	low voltage
rooftop solar	electricity	Y	electricity_distribution_grid	solar rooftop



- ... but no-one needs bother besides us (or new features developers)

# Outline

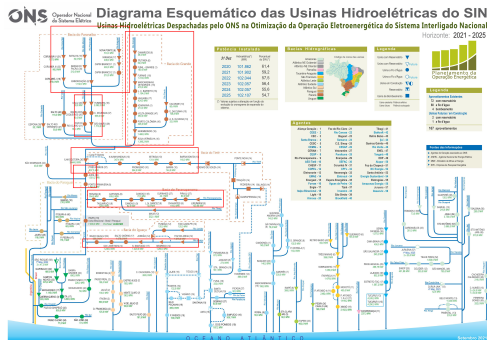
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# Seasonal Storage Valuation – some results I

- SDDPSolver requires convex problem: any of the above  $\Rightarrow$  **useful tricks** (continuous relaxation forward, Lagrangian relaxation backward)

- Brazilian hydro-heavy system: 53 hydro (3 cascade), 98 thermal (coal, gas, nuclear), stochastic inflows (20 scenarios)

- Out-of-sample simulation: 1000 scenarios



	Continuous	Lagrangian
Cost: Avg. / Std.	4.6023e+9 / 1.3608e+9	4.5860e+9 / 1.3556e+9

- Only 0.4% better, but **just changing a few lines in the Configuration** (Lagrangian about 4 times slower, but can be improved)

# Seasonal Storage Valuation – some results II

- Single node (Switzerland)
- 60 stages (1+ year), 37 scenarios, 168 time instants (weekly UC)
- Units: 3 intermittent, 5 thermals, 1 hydro
- Out-of-sample simulation: all 37 scenarios to integer optimality

	Continuous	Lagrangian
Cost: Avg. / Std.	1.3165e+11 / 2.194e+10	1.2644e+11 / 2.167e+10
time	25m	7h30m

- Much longer, but:
  - simulation cost  $\approx$  30m per scenario, largely dominant
  - save 4% just changing a few lines in the configuration
  - LR time can be improved (ParallelBundleSolver not used)

## Seasonal Storage Valuation – some results III

- A single node (France, guess why ...)
- 60 stages (1+ year), 37 scenarios, 168 time instants (weekly UC)
- 83 thermals, 3 intermittent, 2 batteries, 1 hydro
- Out-of-sample simulation: all 37 scenarios to integer optimality

	Continuous	Lagrangian
Cost: Avg. / Std.	3.951e+11 / 1.608e+11	3.459e+11 / 8.903e+10
time	5h43m	7h54m

- Time not so bad (and 3h20m on average simulation per scenario) using `ParallelBundleSolver` with 5 threads per scenario
- That's 14% just changing a few lines in the Configuration
- Starts happening regularly enough to be trusted

# Seasonal Storage Valuation – some (recent) results IV

- Two dedicated top-level servers with (each) 2 AMD Epyc 9654 (2.4Ghz, 96 cores, 192 threads, 384MB cache) with 1.5TB RAM (DDR5-4800)
- 78 stages, 37 scenarios (uncertainties in demand, inflow, intermittent generation), 84 time steps
- 23 nodes (Balkans, Baltics, Benelux, Britain, Eastern Europe, France, Germany, Italy, Portugal, Scandinavia, Switzerland, Spain, “outside”) + 49 lines, 98 thermals, 18 hydros, 60 intermittent, 22 batteries
- Deterministic equivalent would be  $36^{78} \approx 2.5\text{e}+121$  nodes, each  $6.2\text{e}+5$  variables ( $2.5\text{e}+5$  binary) and  $9.3\text{e}+5$  constraints (do the math ...)
- 37 processes (1 per scenario), ParallelBundleSolver with 5 threads

# Seasonal Storage Valuation – a glimpse to the dynamic

- A sample of evolution, continuous VS Lagrangian relaxation
- Using generated SDDP cuts for future-value-of-water as iteration nature

# cuts	Continuous	Lagrangian	gap (%)
50	95030821478	94327497967	0.75
100	92798901757	92381611565	0.45
200	92857020055	93146422115	-0.31
300	92500105416	92231190639	0.29
400	92434329595	92297148794	0.15
500	92446972425	92572975779	-0.14
best	92434329595	92231190639	0.22
Time	18h20m	9d19h	

- ...but gap is  $2e+8$  €: not a bad gain for 10 days' work
- Time to boldly take the last step



# Energy System Investment Problem – some results I

- **Simplified version**: solve SDDP only once, run optimization with fixed value-of-water function + simulation (SDDPGreedySolver)
- EdF EU scenario: 11 nodes (France, Germany, Italy, Switzerland, Eastern Europe, Benelux, Iberia, Britain, Balkans, Baltics, Scandinavia), 20 lines
- Units: 1183 battery, 7 hydro, 518 thermal, 40 intermittent
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Investments: 3 thermal units + 2 transmission lines.
- Average cost: original (operational)  $6.510e+12$   
optimized (investment + operational)  $5.643e+12$
- This is  $\approx 1$  Trillion Euro, 15%
- Running time: ??? hours for value-of-water functions (EdF provided)  
+ 10 hours (4 scenarios in parallel + ParallelBundleSolver with 6 threads) for the investment problem

# Energy System Investment Problem – some results II

- Simplified version (fixed value-of-water with continuous relaxation)
- Same 11 nodes, 19 lines
- **Less** units: 7 hydros, 44 thermals, 24 batteries, and 42 intermittent
- **More** investments: 82 units + 19 transmission lines.
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Average cost: original (operational)  $3.312e+12$   
optimized (investment + operational)  $1.397e+12$
- This is  $\approx$  **2 Trillion Euro**, 137%
- Running time: 48 hours for value-of-water functions (2 nodes = 96 cores)  
+ 5h 20m to solve the investment problem (1 nodes = 48 core)

# Energy System Investment Problem

- The **true version**: value-of-water recomputed anew for each investment
- Still **simplified: only one scenario** (long way to go, but **TwoStageStochasticBlock** and **BendersDecompositionSolver** currently under active development, we'll get there eventually)
- EU scenario: 14 nodes (France, Germany, Italy, Switzerland, Eastern EU, Benelux, Iberia, Britain, Balkans, Baltics, Denmark, Finland, Sweden, Norway), 28 lines, 62 thermals, 54 intermittent, 8 hydros, 39 batteries
- 78 weeks hourly (168h), 37 scenarios (demand, inflow, RES generation)
- Investments: 99 units of all kinds + all transmission lines
- Requires extensive support for **checkpointing and restarts** (but **less** than on CINECA machines that had 24h time limit)

# Energy System Investment Problem: first steps

- Huge problem, so **three steps approach**
  - solve the Seasonal Storage Valuation with initial system (no investment)
  - solve Energy System Investment Problem with fixed value-of-water function out of SDDP (simulation-based optimization)
  - improve investment by dynamically recomputing value-of-water at every iteration
- Original system cost: (operational)  $3.467\text{e}+12$   
Optimized cost: operational  $4.505\text{e}+11$  + investment  $2.284\text{e}+11$  =  
total  $6.789\text{e}+11$
- **Half an order of magnitude** saving (suspect most **value of lost load**),  
511% better investing on just 4 lines and 10 hydrogen power plants
- Running time: 15h18m for future cost function of the original system,  
5h18m simulation-based investment problem (74 threads max)

# The Little-Big Kahuna results

- Starting from previous solution, optimize with variable value-of-water
  - iteration 0: op.  $4.505\text{e}+11$  + inv.  $2.284\text{e}+11$  = total  $6.789\text{e}+11$  (1.8h)  
(very sparse investment decision)

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  - iteration 4: **nope, sorry, still running**
- Already a factor of 2 better than original system (no investment)
- Using LPs in SDDP (many numerical issues), Lagrangian will be better and will be able to use way more threads (ParallelBundleSolver)
- Will improve over the fixed value-of-water, just not there as yet

# The Big Kahuna results

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- Roll of drums ...

# The Big Kahuna results

- Roll of drums . . . suspenseful pause . . .

# The Big Kahuna results

- Roll of drums ... suspenseful pause ...
- **JUST KIDDING**: still in the design phase, forget about it (for today)
- Clearly **extremely challenging** problem, need all the help we can get
- But we **are getting there**, thanks to SMS++

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# Conclusions

- Want to solve ludicrously large problem? SMS++ is here for you
- Allows exploiting multiple nested heterogeneous structure,  $\approx$  the only framework designed for huge-scale (stochastic or not) problems
- Could become really useful after having attracted mindshare, self-reinforcing loop very hard to start



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- Hefty, possibly unrealistic, sough-after impacts:
  - improve collaboration and code reuse, reduce huge code waste (I ♥ coding, breaks my ♥)
  - significantly increase the addressable market of decomposition
  - a much-needed step towards higher uptake of parallel methods
  - the missing marketplace for specialised solution methods

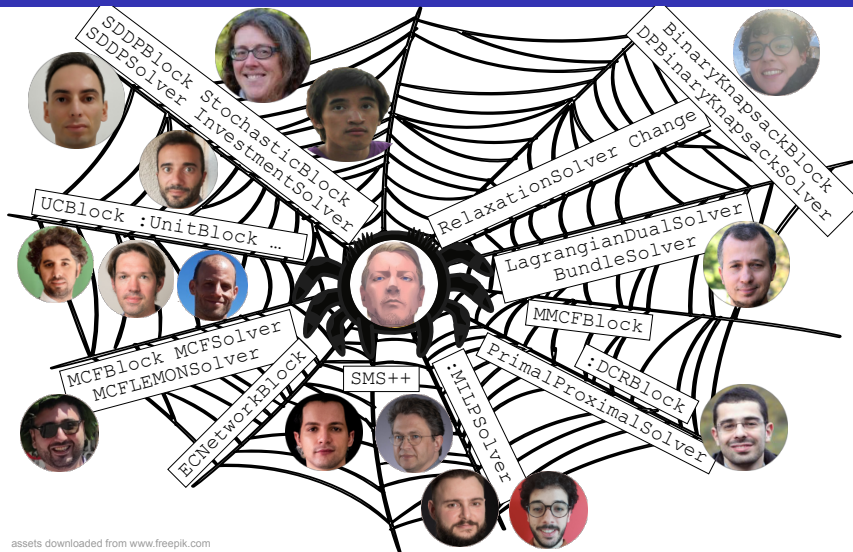
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- A community-building effort as much as a software product: is it working?

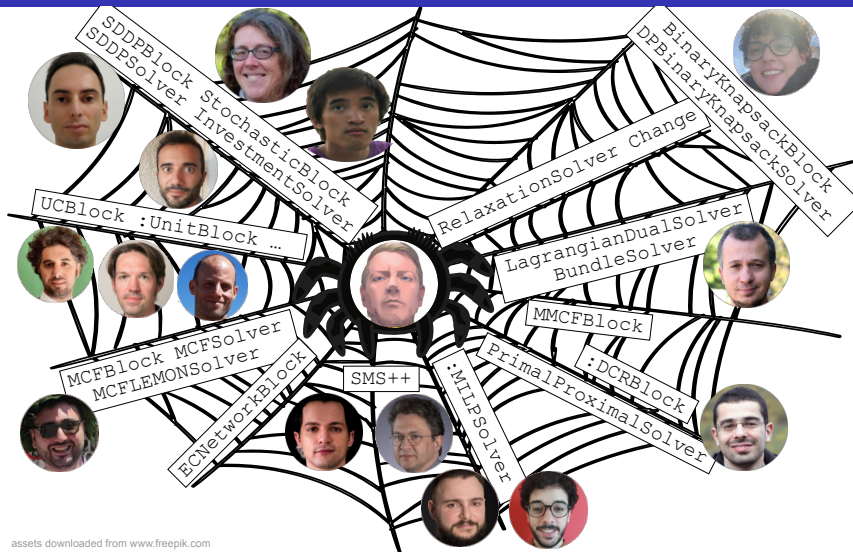
...see it for yourself




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- **Not** yet a thriving community, but **labouring to reach critical mass**

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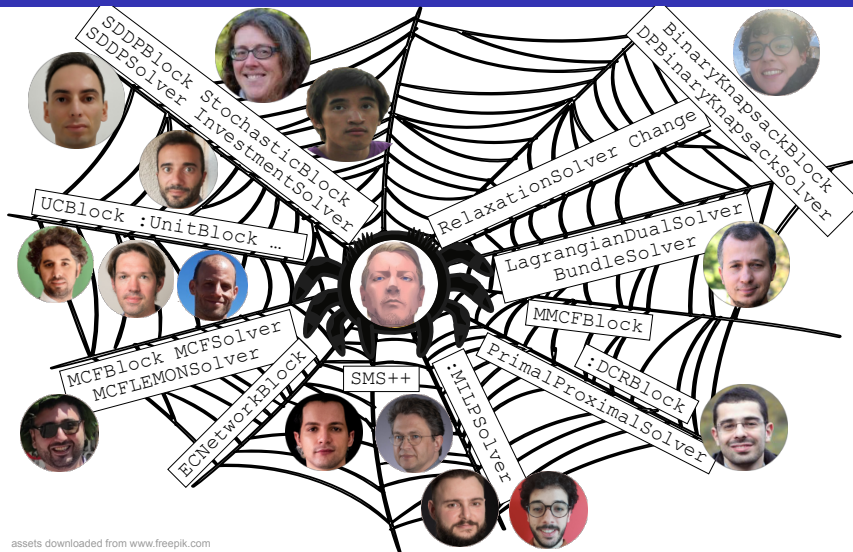


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- Plenty of room in the Hotel California 



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- **Not** yet a thriving community, but **labouring to reach critical mass**
- Plenty of room in the spiderweb, **be my guest** 🧑🏻

