

# Graphs (Γράφοι)

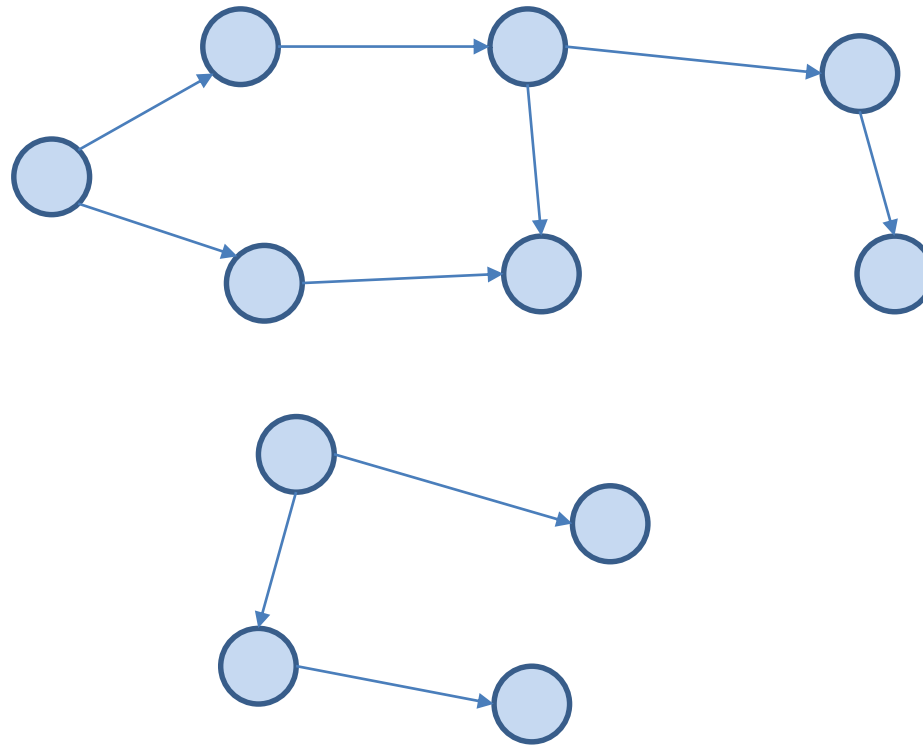
Κ08 Δομές Δεδομένων και Τεχνικές Προγραμματισμού

Κώστας Χατζηκοκολάκης

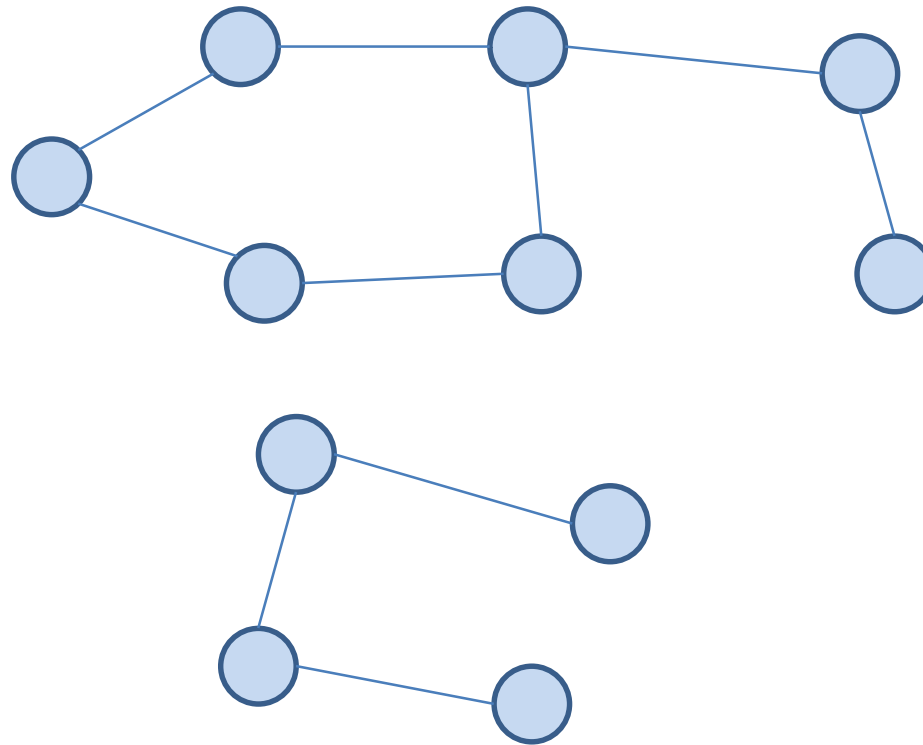
# Graphs

- **Graphs** are collections of nodes in which various pairs are connected by line segments. The nodes are usually called **vertices** (κορυφές) and the line segments **edges** (ακμές).
- Graphs are **more general than trees**. Graphs are allowed to have cycles and can have more than one connected component.
- Some authors use the terms **nodes** (κόμβοι) and **arcs** (τόξα) instead of vertices and edges.

# Example of Graphs (Directed)



# Example of Graphs (Undirected)



# Examples of Graphs

- Transportation networks
- **Interesting problem:** What is the path with one or more stops of shortest overall distance connecting a starting city and a destination city?

# Examples

- A network of oil pipelines
- **Interesting problem:** What is the maximum possible overall flow of oil from the source to the destination?

# Examples

- The Internet
- **Interesting problem:** Deliver an e-mail from user A to user B

# Examples

- The Web
- **Interesting problem:** What is the PageRank of a Web site?



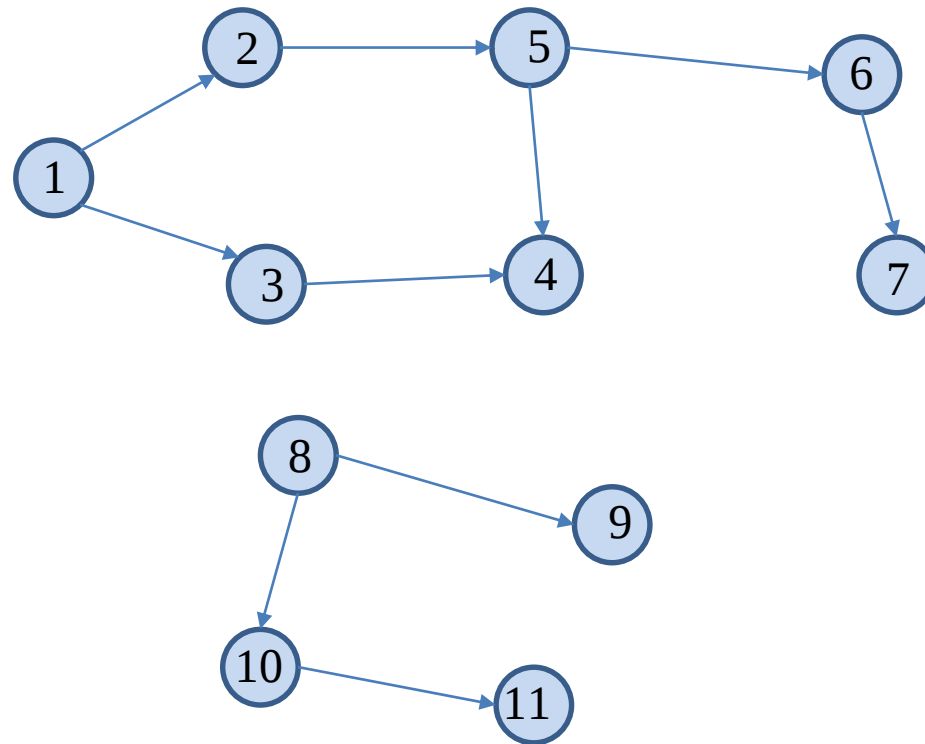
# Examples

- The Facebook social network
- **Interesting problem:** Are John and Mary connected? What interesting clusters exist?

# Formal Definitions

- A **graph**  $G = (V, E)$  consists of a set of **vertices**  $V$  and a set of **edges**  $E$ , where the edges in  $E$  are formed from pairs of **distinct** vertices in  $V$ .
- If the edges have directions then we have a **directed graph** (**κατευθυνόμενο γράφο**) or **digraph**. In this case edges are ordered pairs of vertices e.g.,  $(u, v)$  and are called **directed**. If  $(u, v)$  is a directed edge then  $u$  is called its **origin** and  $v$  is called its **destination**.
- If the edges do not have directions then we have an **undirected graph** (**μη-κατευθυνόμενος γράφο**). In this case edges are unordered pairs of vertices e.g.,  $\{u, v\}$  and are called **undirected**.
- For simplicity, we will use the directed pair notation noting that in the undirected case  $(u, v)$  is the same as  $(v, u)$ .
- When we say simply graph, we will mean an undirected graph.

# Example of a Directed Graph

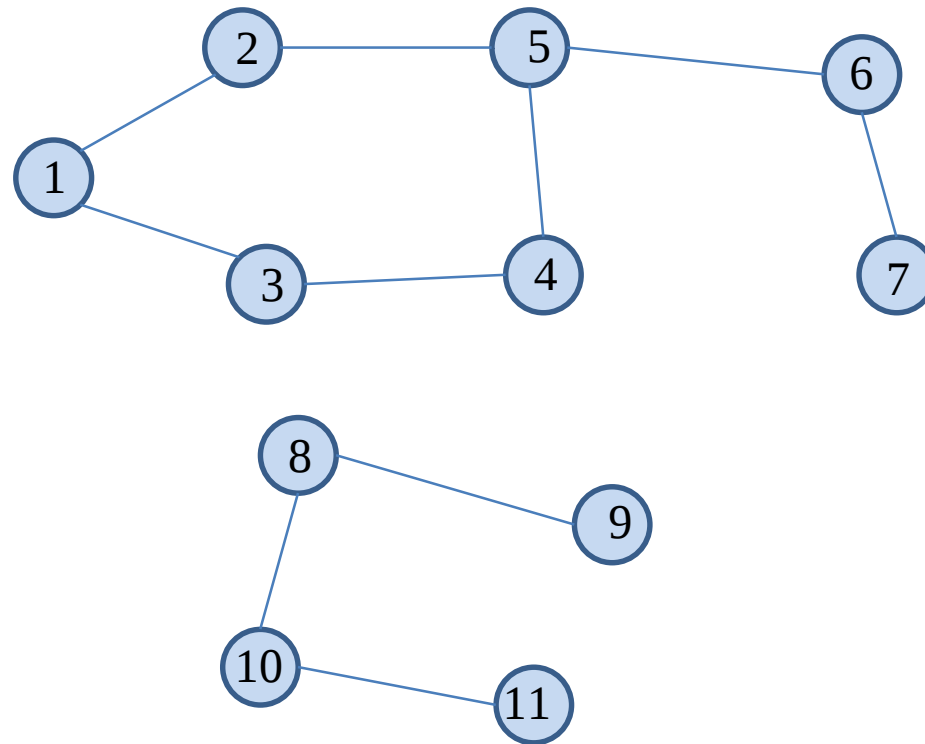


$$G = (V, E)$$

$$V = 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11$$

$$E = (1, 2), (1, 3), (2, 5), (3, 4), (5, 4), (5, 6), (6, 7), (8, 9), (8, 10), (10, 11)$$

# Example of an Undirected Graph



$$G = (V, E)$$

$$V = 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11$$

$$E = (1, 2), (1, 3), (2, 5), (3, 4), (5, 4), (5, 6), (6, 7), (8, 9), (8, 10), (10, 11)$$

# More Definitions

- Two different vertices  $v_i, v_j$  in a graph  $G = (V, E)$  are said to be **adjacent (γειτονικές)** if there exists an edge  $(v_i, v_j) \in E$ .
- An edge is said to be **incident (προσπίπτουσα)** on a vertex if the vertex is one of the edge's endpoints.
- A **path (μονοπάτι)**  $p$  in a graph  $G = (V, E)$ , is a sequence of vertices of  $V$  of the form  $p = v_1 v_2 \dots v_n, (n \geq 2)$  in which each vertex  $v_i$ , is adjacent to the next one  $v_{i+1}$  (for  $1 \leq i \leq n - 1$ ).
- The **length** of a path is the number of edges in it.
- A path is **simple** if each vertex in the path is distinct.
- A **cycle** is a path  $p = v_1 v_2 \dots v_n$  of length greater than one that begins and ends at the same vertex (i.e.,  $v_1 = v_n$ ).

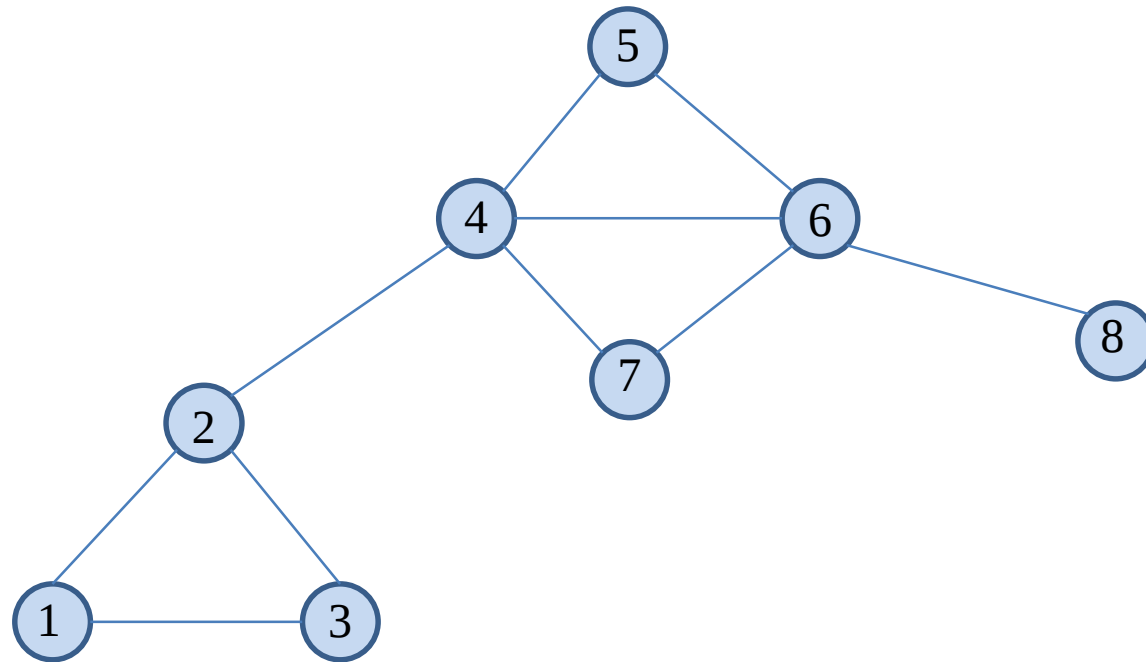
# Definitions

- A **directed path** is a path such that all edges are directed and are traversed along their direction.
- A **directed cycle** is similarly defined.

# Definitions

- A **simple cycle** is a path that travels through three or more **distinct** vertices and connects them into a loop.

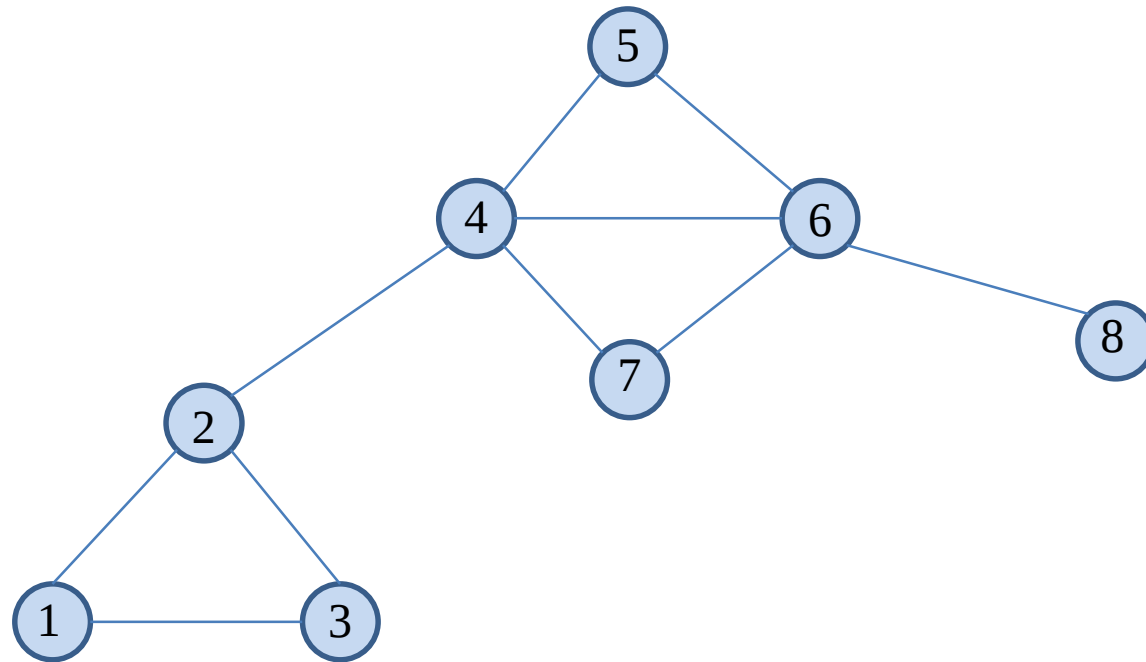
# Example



**Four simple cycles:**  $(1,2,3,1)$   $(4,5,6,7,4)$   $(4,5,6,4)$   $(4,6,7,4)$

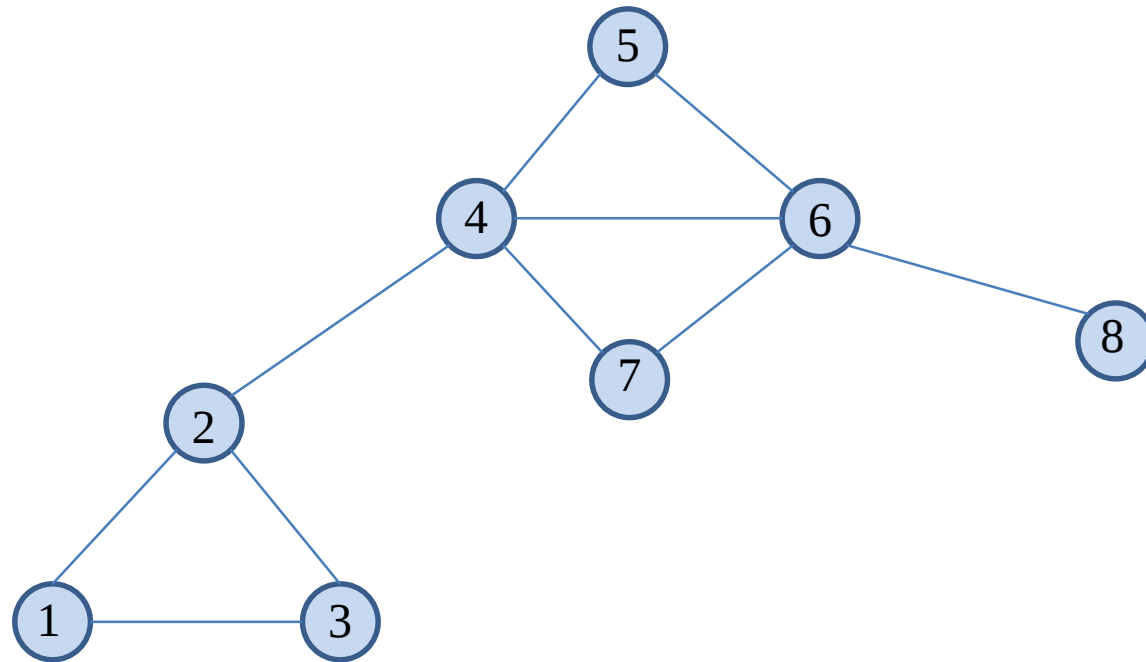


# Example



**Two non-simple cycles:**  $(1,2,1)$   $(4,5,6,4,7,6,4)$

# Example



**A path that is not a cycle:** (1,2,4,6,8)

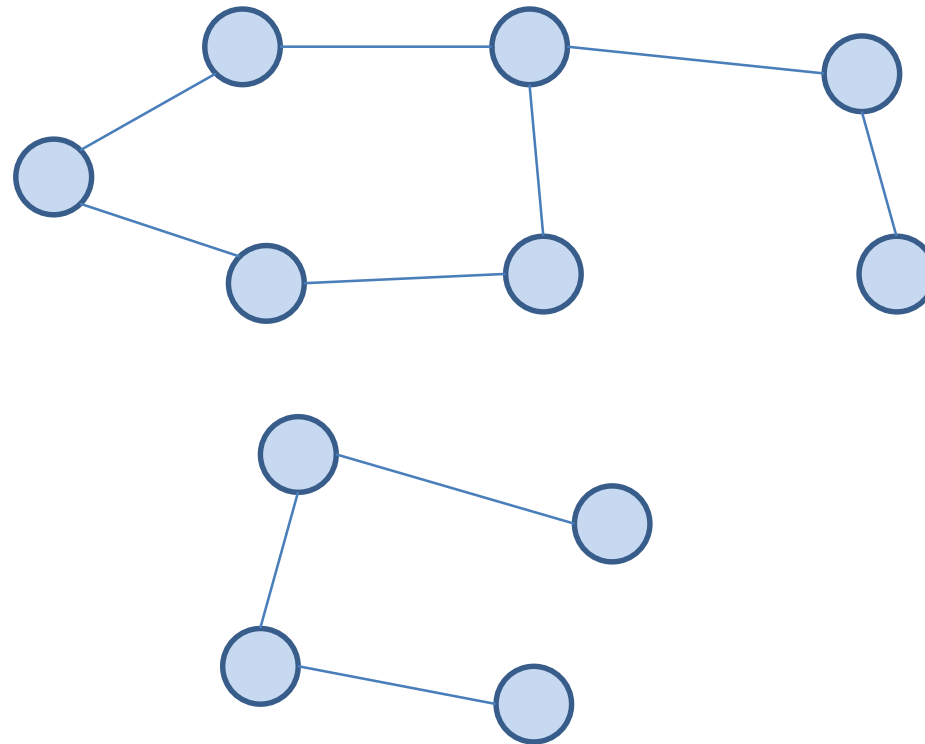
# Connectivity and Components

- Two vertices in a graph  $G = (V, E)$  are said to be **connected** (**συνδεδεμένες**) if there is a path from the first to the second in  $G$
- Formally, if  $x \in V$  and  $y \in V$ , where  $x \neq y$ , then  $x$  and  $y$  are **connected** if there exists a path  $p = v_1 v_2 \dots v_n \in G$  in such that  $x = v_1$  and  $y = v_n$

# Connectivity and Components

- In the graph  $G = (V, E)$ , a **connected component (συνεκτική συνιστώσα)** is a subset  $S$  of the vertices  $V$  that are all connected to one another.
- A connected component  $S$  of  $G$  is a **maximal connected component (μέγιστη συνεκτική συνιστώσα)** provided there is no bigger subset  $T$  of vertices in  $V$  such that  $T$  properly contains  $S$  and such that  $T$  itself is a connected component of  $G$ .
- An undirected graph  $G$  can always be separated into maximal connected components  $S_1, S_2, \dots, S_n$  such that  $S_i \cap S_j = \emptyset$  whenever  $i \neq j$ .

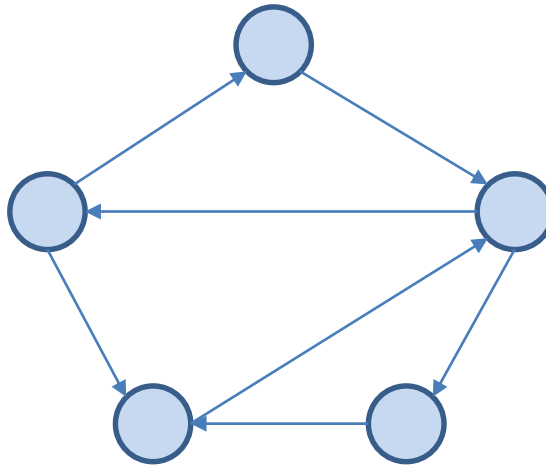
# Example of Undirected Graph and its Separation into Two Maximal Connected Components



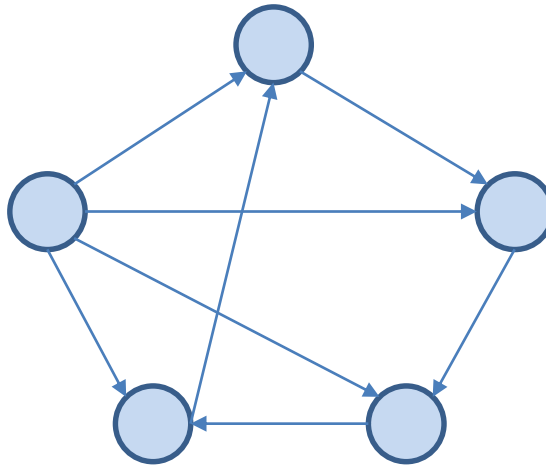
# Connectivity and Components in Directed Graphs

- A subset  $S$  of vertices in a **directed** graph  $G$  is **strongly connected** (**ισχυρά συνεκτικό**) if for each pair of distinct vertices  $(v_i, v_j)$  in  $S$ ,  $v_i$  is connected to  $v_j$  **and**  $v_j$  is connected to  $v_i$ .
- A subset  $S$  of vertices in a **directed** graph  $G$  is **weakly connected** (**ασθενώς συνεκτικό**) if for each pair of distinct vertices  $(v_i, v_j)$  in  $S$ ,  $v_i$  is connected to  $v_j$  **or**  $v_j$  is connected to  $v_i$ .

# Example: A Strongly Connected Digraph



# Example: A Weakly Connected Digraph

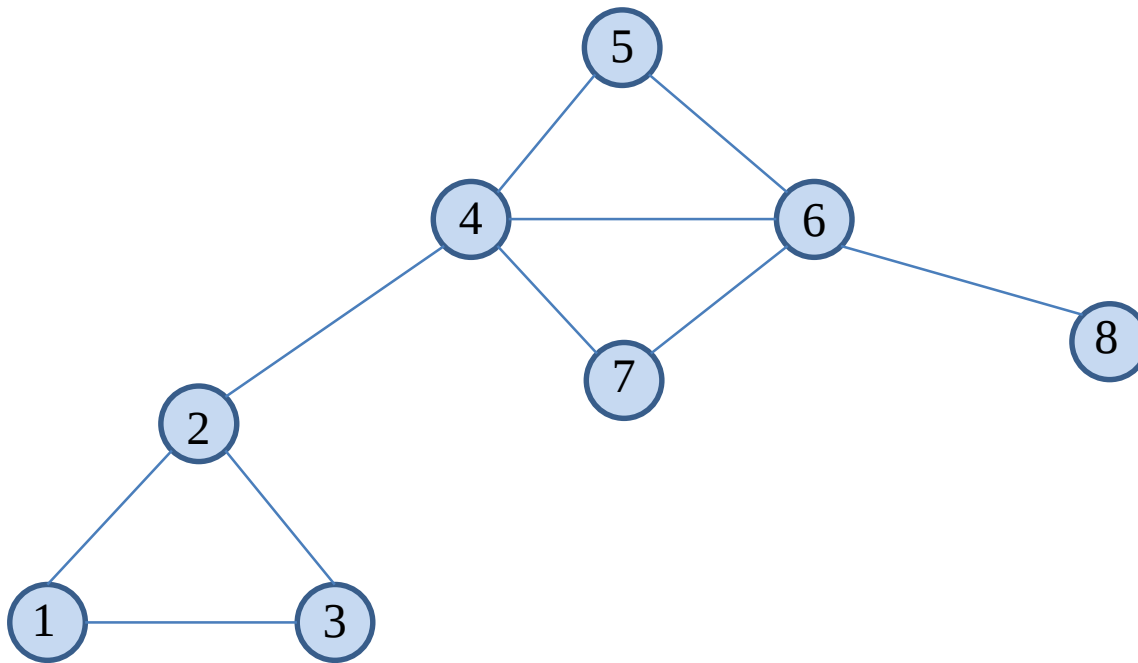




# Degree in Undirected Graphs

- In an undirected graph  $G$  the **degree** (βαθμός) of vertex  $x$  is the number of edges  $e$  in which  $x$  is one of the endpoints of  $e$ .
- The degree of a vertex  $x$  is denoted by  $\deg(x)$ .

# Example



The degree of node 1 is 2.

The degree of node 4 is 4.

The degree of node 8 is 1.

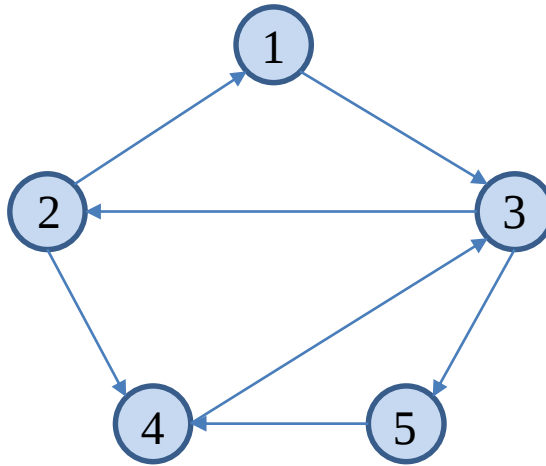
# Predecessors and Successors in Directed Graphs

- If  $x$  is a vertex in a **directed** graph  $G = (V, E)$  then the set of **predecessors (προηγούμενων)** of  $x$  denoted by  $\text{Pred}(x)$  is the set of all vertices  $y \in V$  such that  $(y, x) \in E$ .
- Similarly the set of **successors (επόμενων)** of  $x$  denoted by  $\text{Succ}(x)$  is the set of all vertices  $y \in V$  such that  $(x, y) \in E$ .

# In-Degree and Out-Degree in Directed Graphs

- The **in-degree** of a vertex  $x$  is the number of predecessors of  $x$
- The **out-degree** of a vertex  $x$  is the number of successors of  $x$
- We can also define the in-degree and the out-degree by referring to the **incoming** and **outgoing** edges of a vertex.
- The in-degree and out-degree of a vertex  $x$  are denoted by  $\text{indeg}(x)$  and  $\text{outdeg}(x)$  respectively.

# Example



The in-degree of node 4 is 2. The out-degree of node 4 is 1.

# Proposition

- If  $G$  is an undirected graph with  $m$  edges, then

$$\sum_{v \in G} \deg(v) = 2m$$

.

- Proof?
  - Each edge is counted twice

# Proposition

- If  $G$  is a directed graph with  $m$  edges, then

$$\sum_{v \in G} \text{indeg}(v) = \sum_{v \in G} \text{outdeg}(v) = m$$

- Proof?
  - Each edge is counted once

# Proposition

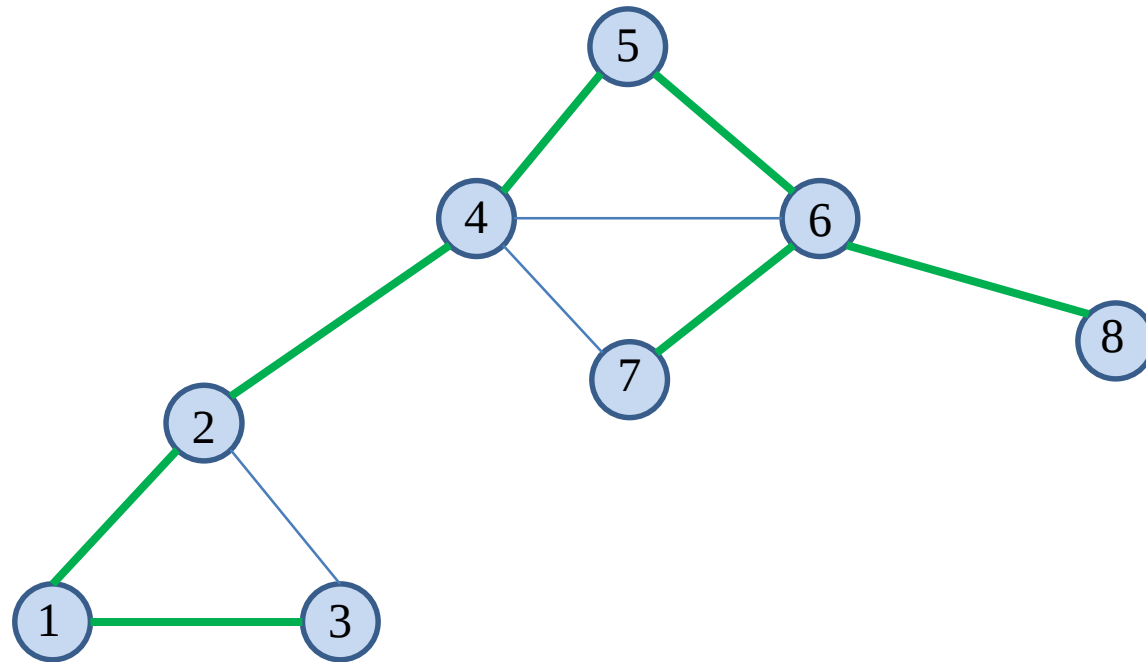
- Let  $G$  be a graph with  $n$  vertices and  $m$  edges. If  $G$  is undirected, then  $m \leq \frac{n(n-1)}{2}$  and if  $G$  is directed, then  $m \leq n(n-1)$ .
- Proof?
  - If  $G$  is undirected then the maximum degree of a vertex is  $n-1$ . Therefore, from the previous proposition about the sum of the degrees, we have  $2m \leq n(n-1)$ .
  - If  $G$  is directed then the maximum in-degree of a vertex is  $n-1$ . Therefore, from the previous proposition about the sum of the in-degrees, we have  $m \leq n(n-1)$ .



# More definitions

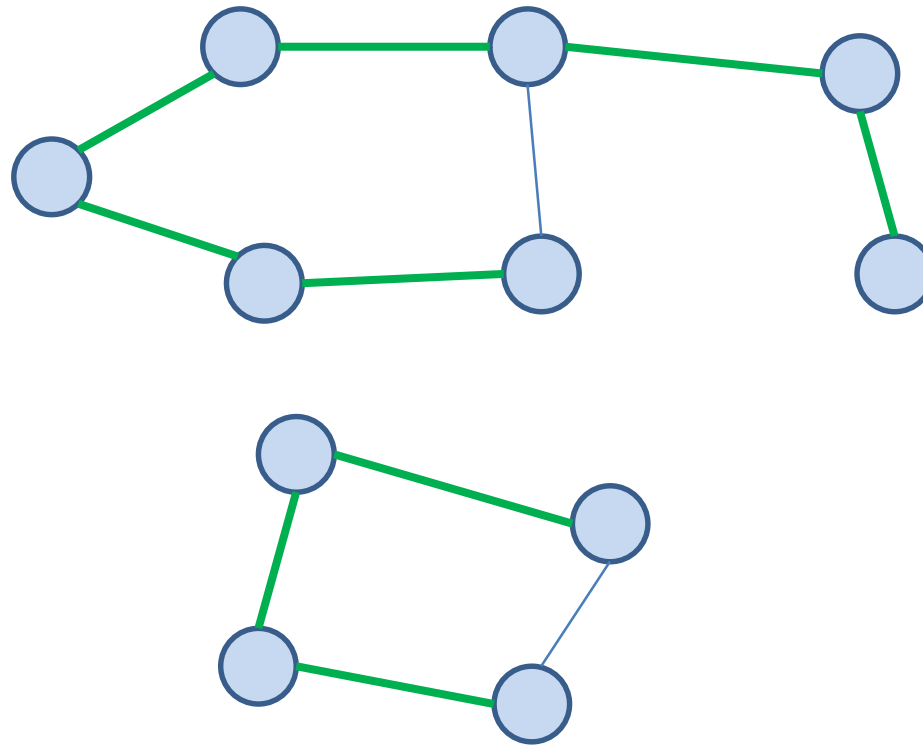
- A **subgraph (υπογράφος)** of a graph  $G$  is a graph  $H$  whose vertices and edges are subsets of the vertices and edges of  $G$  respectively.
- A **spanning subgraph (υπογράφος επικάλυψης)** of  $G$  is a subgraph of  $G$  that contains all the vertices of  $G$ .
- A **forest (δάσος)** is a graph without cycles.
- A **free tree (ελεύθερο δένδρο)** is a connected forest i.e., a connected graph without cycles. The trees that we studied in earlier lectures are **rooted trees (δένδρα με ρίζα)** and they are different than free trees.
- A **spanning tree (δένδρο επικάλυψης)** of a graph is a spanning subgraph that is a free tree.

# Example



The thick green lines define a spanning tree of the graph.

# Example

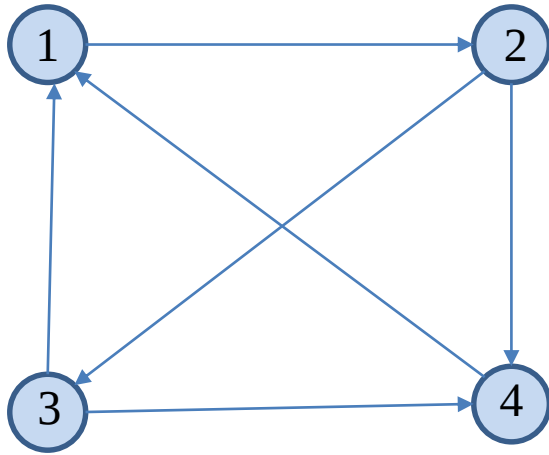


The thick green lines define a forest which consists of two free trees.

# Graph Representations: Adjacency Matrices

- Let  $G = (V, E)$  be a graph. Suppose we number the vertices in  $V$  as  $v_1, v_2 \dots v_n$
- The **adjacency matrix (πίνακας γειτνίασης)** corresponding to  $G$  is an  $n \times n$  matrix such that  $T[i, j] = 1$  if there is an edge  $(v_i, v_j) \in E$ , and  $T[i, j] = 0$  if there is no such edge in  $E$ .

# Example



A graph G

	1	2	3	4
1	0	1	0	0
2	0	0	1	1
3	1	0	0	1
4	1	0	0	0

The adjacency matrix for graph G

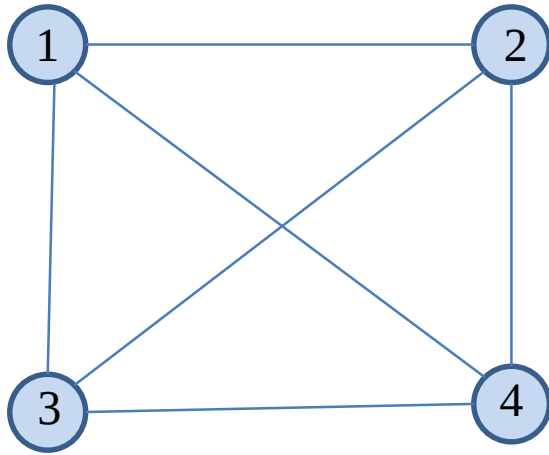
# Adjacency Matrices

- The adjacency matrix of an **undirected graph**  $G$  is a **symmetric matrix** i.e.,  $T[i, j] = T[j, i]$  for all and in the range  $1 \leq i, j \leq n$
- The adjacency matrix for a **directed graph** need not be symmetric.

# Adjacency Matrices

- The **diagonal entries** in an adjacency matrix (of a directed or undirected graph) **are zero**, since graphs as we have defined them are not permitted to have looping self-referential edges that connect a vertex to itself.

# Example



An undirected graph G

	1	2	3	4
1	0	1	1	1
2	1	0	1	1
3	1	1	0	1
4	1	1	1	0

The adjacency matrix for graph G



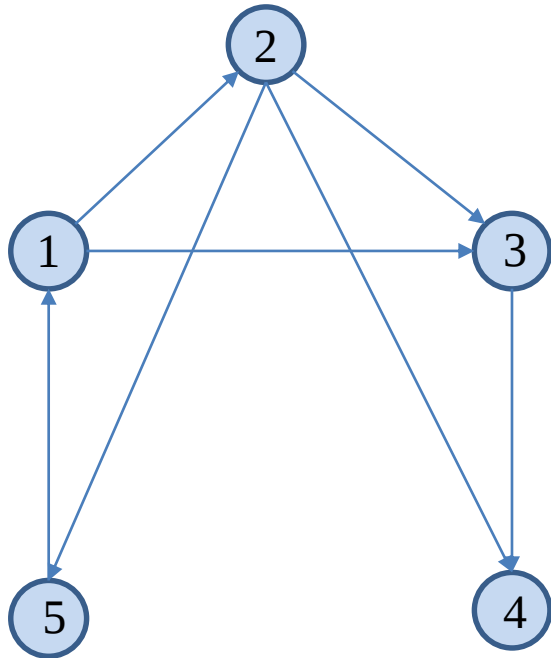
# Adjacency Sets

- Another way to define a graph  $G = (V, E)$  is to specify **adjacency sets** (**σύνολα γειτνίασης**) for each vertex in  $V$ .
- Let  $V_x$  stand for the set of all vertices **adjacent** to  $x$  in an undirected graph  $G$  or the set of all vertices that are **successors** of  $x$  in a directed graph  $G$ .
- If we give both the vertex set  $v$  and the collection  $A = \{V_x | x \in V\}$  of adjacency sets for each vertex in then we have given enough information to define the graph  $G$ .

# Graph Representations: Adjacency Lists

- Another family of representations for a graph uses **adjacency lists** (λίστες γειτνίασης) to represent the adjacency set  $V_x$  for each vertex  $x$  in the graph.

# Example Directed Graph

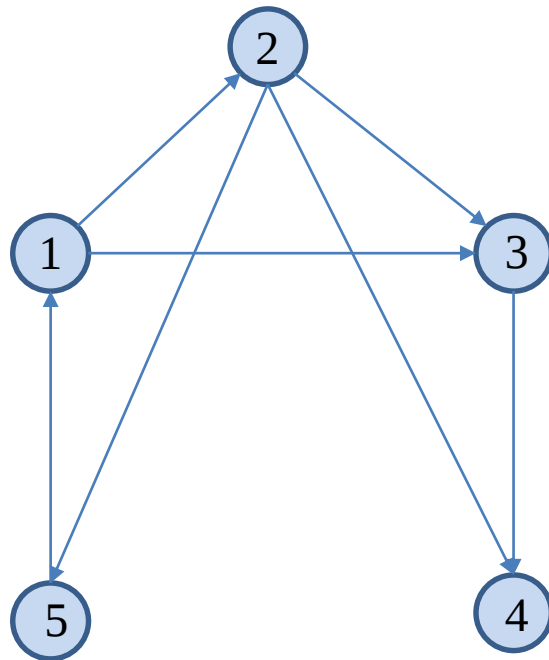


Adirected graph G

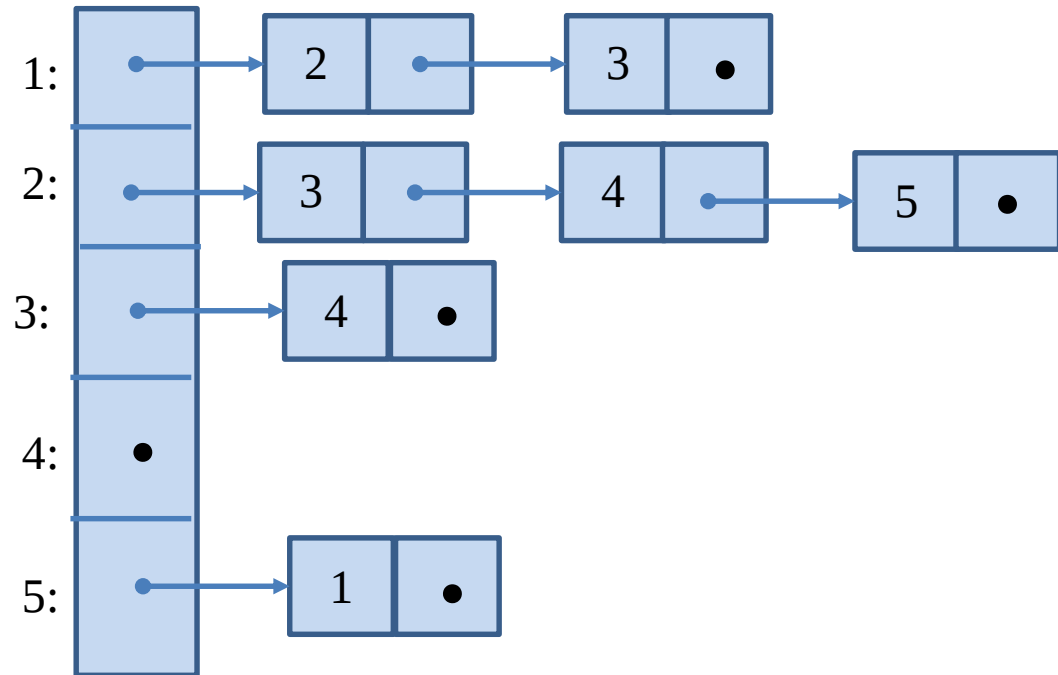
Vertex Number	Out Degree	Adjacency list
1	2	2 3
2	3	3 4 5
3	1	4
4	0	
5	1	1

The **sequential** adjacency lists for graph G. Notice that vertices are listed in their **natural order**.

# Example Directed Graph

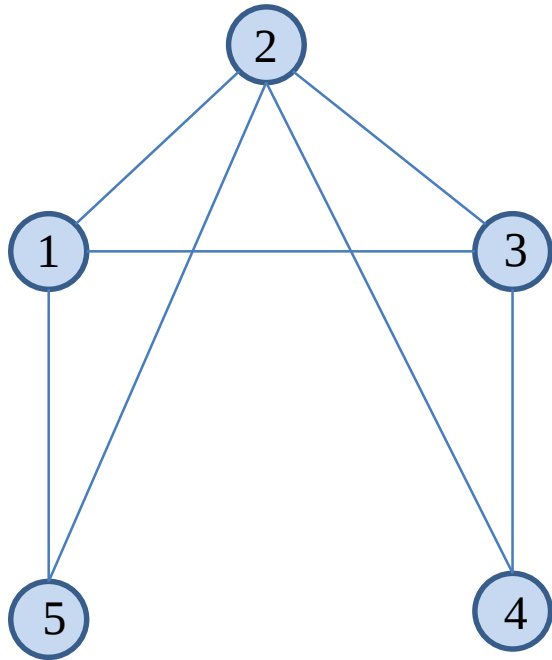


A directed graph G



The **linked** adjacency lists for graph G.  
Notice that vertices in a list are organized  
according to their **natural order**.

# Example Undirected Graph



An undirected graph G

Vertex Number	Degree	Adjacency list
1	3	2 3 5
2	4	1 3 4 5
3	3	1 2 4
4	2	2 4
5	2	1 2

The sequential adjacency lists for graph G

# Graph Searching

- To search a graph  $G$ , we need to visit all vertices of  $G$  in some systematic order.
- Each vertex  $v$  can be a structure with a `bool` valued member `visited`. Visited which is initially `false` for all vertices of  $G$ . When we visit  $v$ , we will set it to `true`.

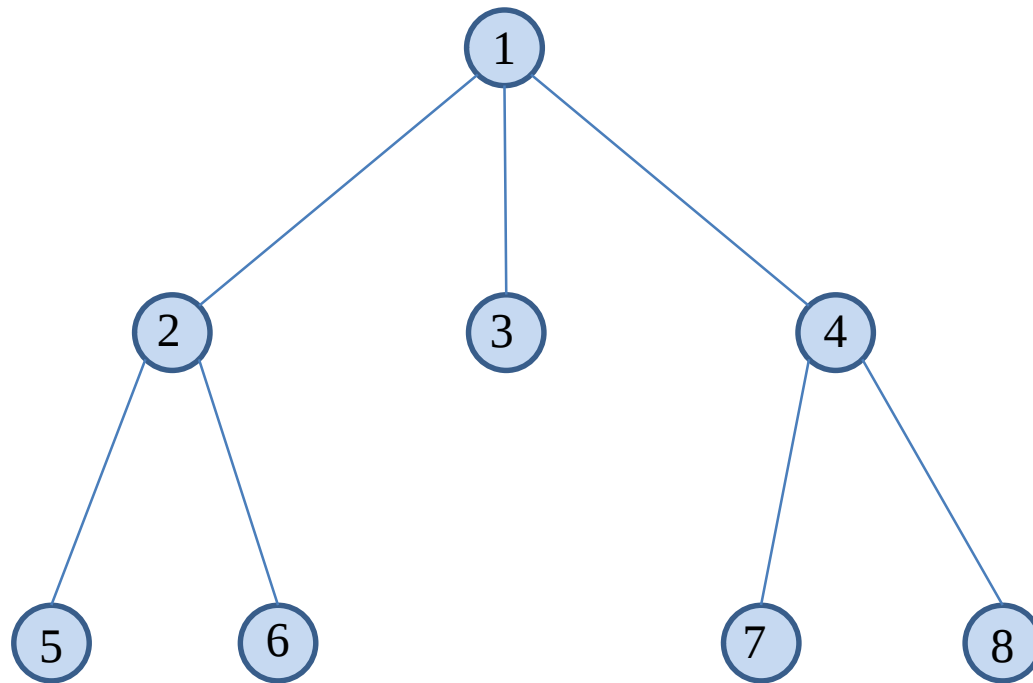
# An Algorithm for Graph Searching

*// Ψευδοκώδικας, επίσκεψη όλων των κόμβων του γράφου*

```
void graph_search(G) {  
    Let  $G = (V, E)$  be a graph  
    Let C be an empty container  
  
    for (each vertex  $x$  in  $V$ ) {  
         $x.visited = false$ ;  
    }  
    Insert  $v$  into C;  
  
    while (C is non-empty) {  
        Remove a vertex  $x$  from container C;  
        if ( $!x.visited$ ) {  
            visit( $x$ );  
             $x.visited = true$ ;  
            for (each vertex  $w$  adjacent to  $x$ ) {  
                if ( $!w.visited$ )  
                    Insert  $w$  into C;  
            }  
        }  
    }  
}
```

# Graph Searching

Interesting case: the container  $C$  is a stack.

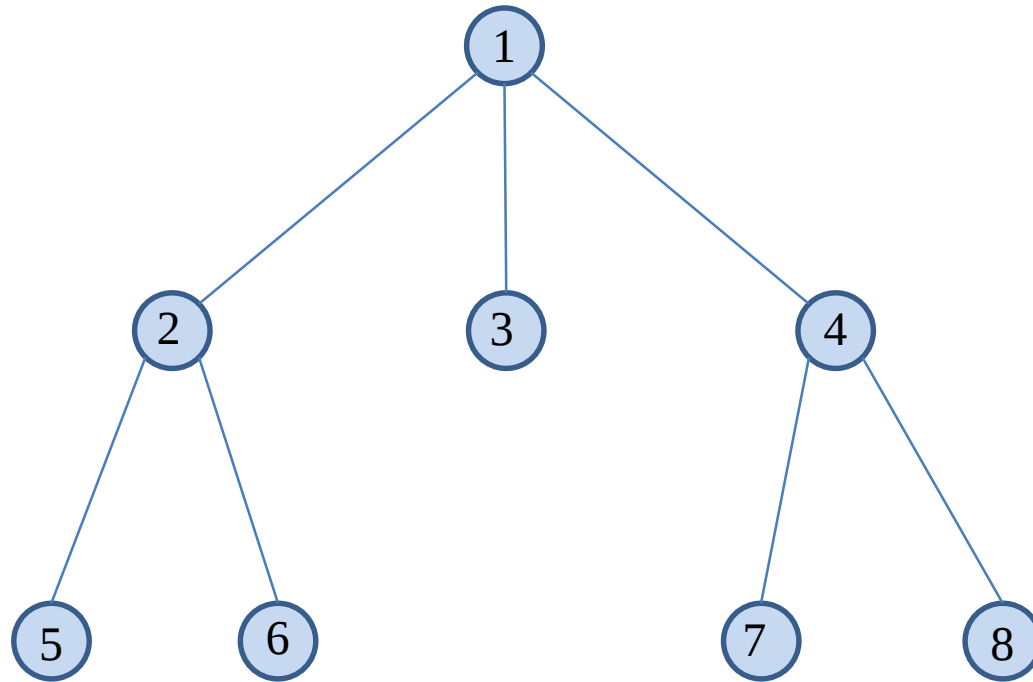


In what order vertices are visited?



# Graph Searching

Eg. the container  $C$  is a stack.



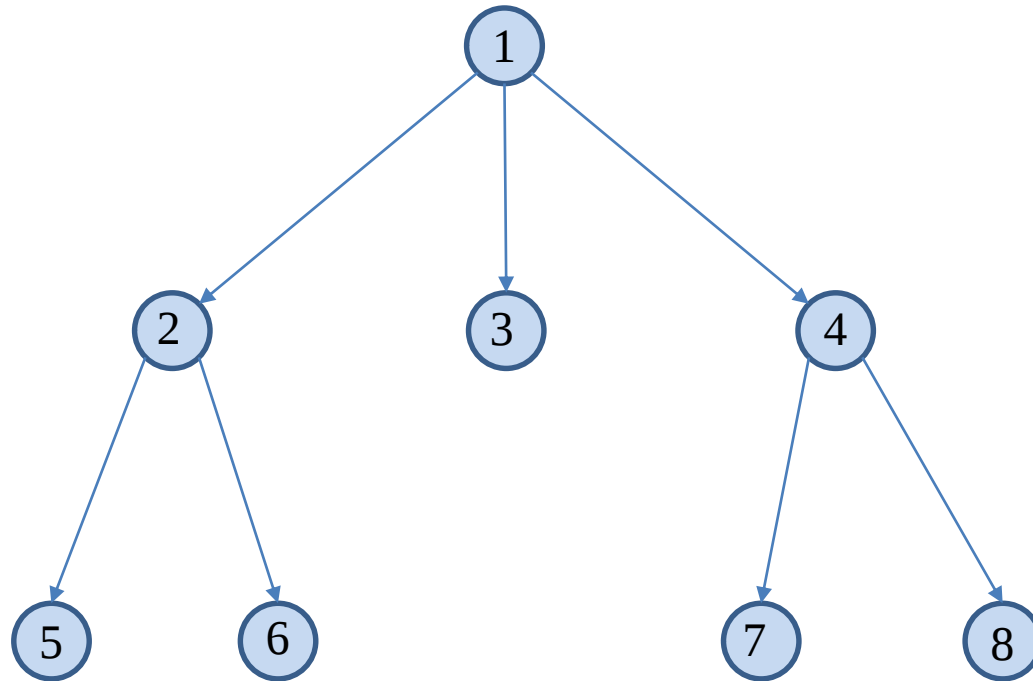
The vertices are visited in the order 1, 4, 8, 7, 3, 2, 6, 5.

# Depth-First Search (DFS)

- When  $C$  is a **stack**, the tree in the previous example is searched in **depth-first order**.
- **Depth-first search (αναζήτηση πρώτα κατά βάθος)** at a vertex always goes down (by visiting unvisited children) before going across (by visiting unvisited brothers and sisters).
- Depth-first search of a graph is analogous to a **pre-order traversal** of an ordered tree.

# Graph Searching

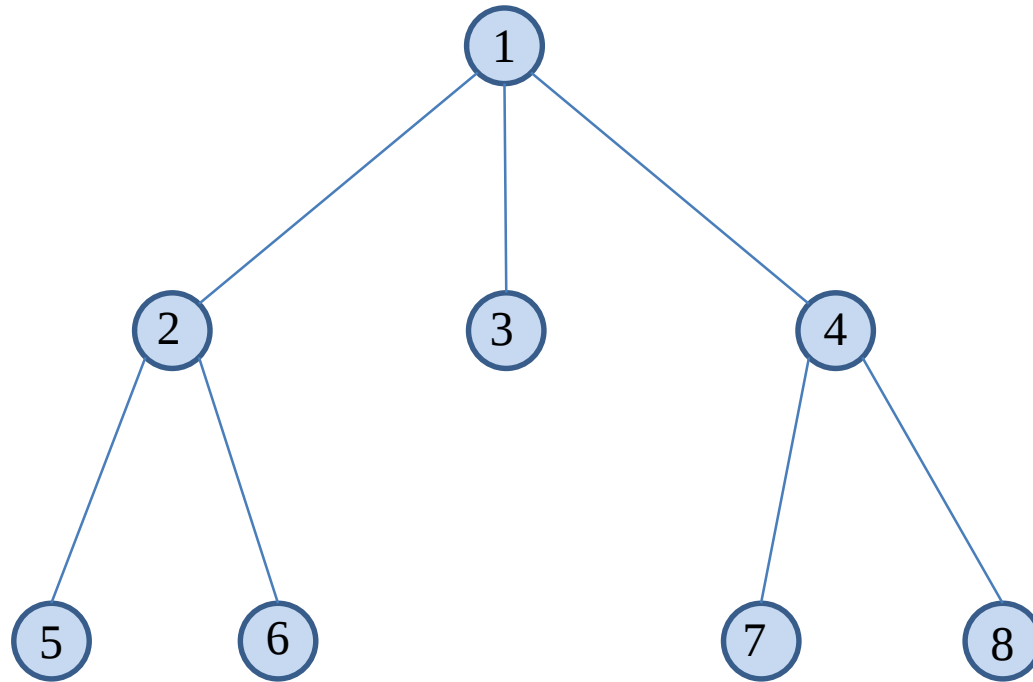
Another interesting case: the container  $C$  is a queue.



What is the order vertices are visited?

# Graph Searching

Another interesting case: the container  $C$  is a queue.

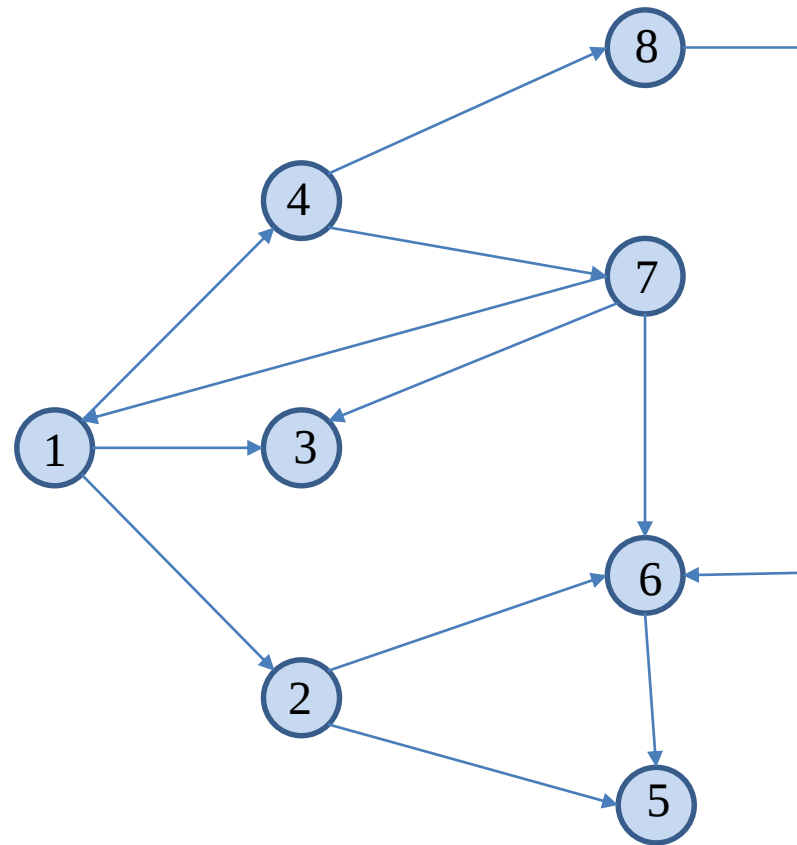


The vertices are visited in the order 1, 2, 3, 4, 5, 6, 7 and 8.

# Breadth-First Search (BFS)

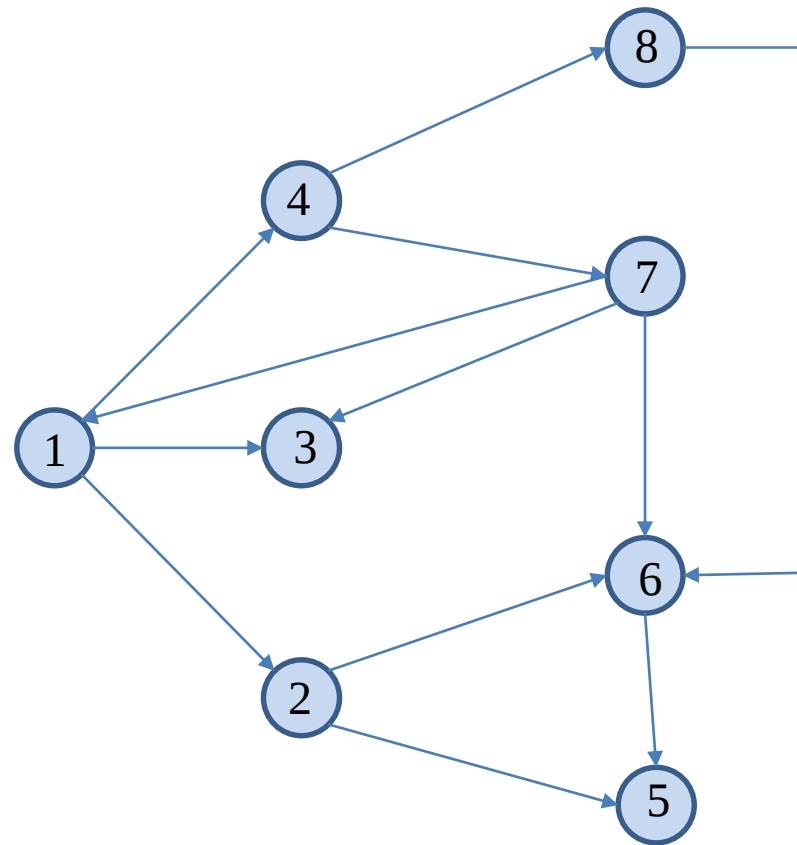
- When  $C$  is a **queue**, the tree in the previous example is searched in **breadth-first order**.
- **Breadth-first search (αναζήτηση πρώτα κατά πλάτος)** at a vertex always goes broad before going deep.
- Breadth-first traversal of a graph is analogous to a traversal of an ordered tree that visits the nodes of the tree in **level-order**.
- BFS subdivides the vertices of a graph in **levels**. The starting vertex is at level 0, then we have the vertices adjacent to the starting vertex at level 1, then the vertices adjacent to these vertices at level 2 etc.

# Example



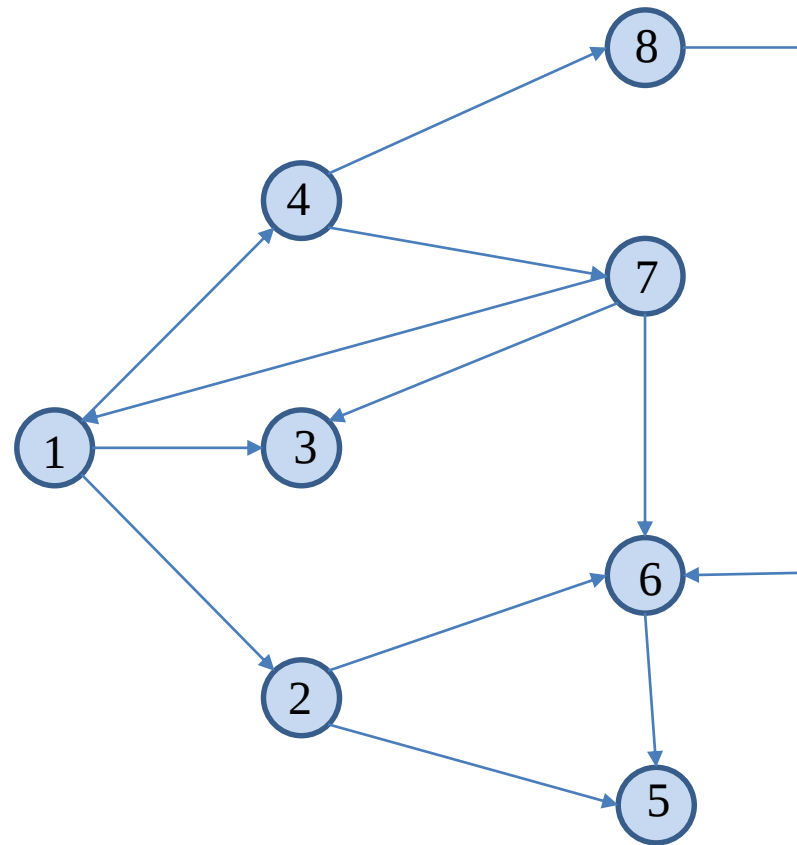
What is the order of visiting vertices for DFS?

# Example



Depth-first search visits the vertices in the order 1, 4, 8, 6, 5, 7, 3 and 2

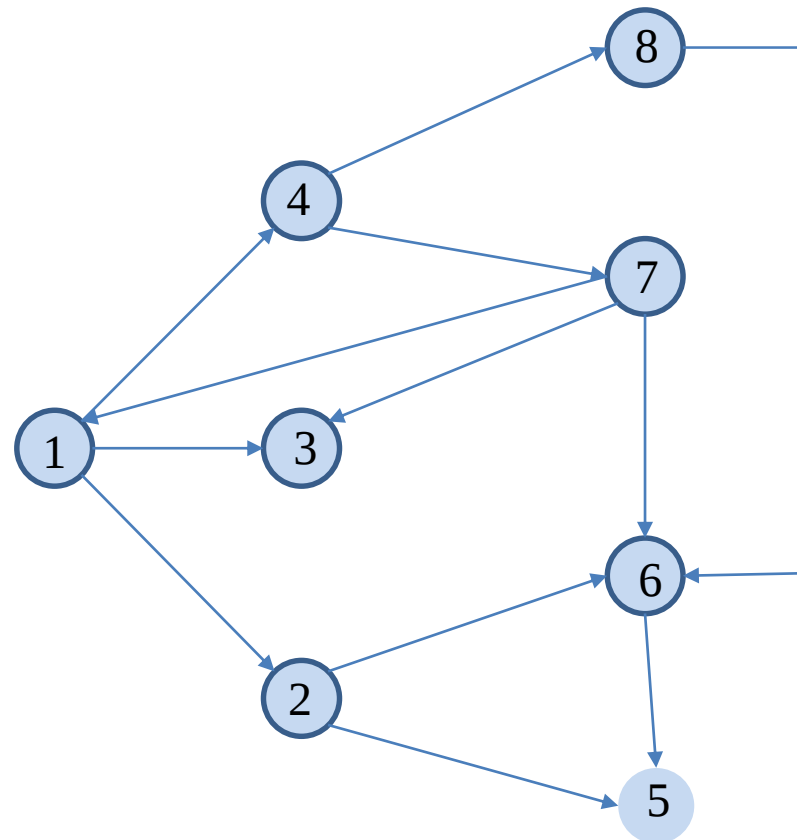
# Example



What is the order of visit for BFS?



# Example



Breadth-first search visits the vertices in the order 1, 2, 3, 4, 5, 6, 7 and 8.

# Exhaustive Search

- Either the stack version or the queue version of the algorithm `GraphSearch` will visit every vertex in a graph  $G$  provided that  $G$  consists of a single strongly connected component.
- If this is not the case, then we can enumerate all the vertices of  $G$  and run `GraphSearch` starting from each one of them in order to visit all the vertices of  $G$ .

# Exhaustive Search

```
void graph_exhaustive_search(G) {  
    Let  $G = (V, E)$  be a graph.  
    for (each vertex  $v$  in  $G$ ) {  
        graph_search( $G, v$ )  
    }  
}
```

# Recursive DFS

- DFS can be also written recursively
- The stack is essentially replaced by the **function call stack**

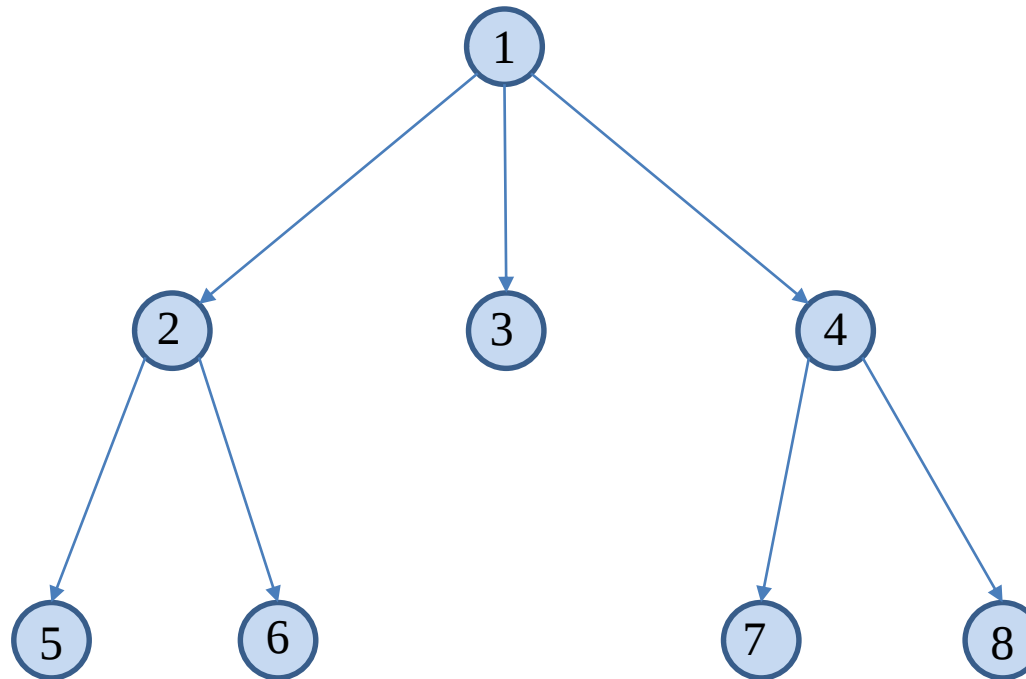
# Recursive DFS

*// Ψευδοκώδικας, επίσκεψη όλων των κόμβων του γράφου*

```
void graph_dfs(G) {  
    for (each vertex x in V) {  
        x.visited = false;  
    }  
    for (each vertex x in V) {  
        if (!x.visited)  
            traverse(G, x);  
    }  
}  
  
void traverse(G, x) {  
    visit(x);  
    x.visited = true;  
  
    for (each vertex w adjacent to v) {  
        if (!w.visited)  
            traverse(G, w);  
    }  
}
```

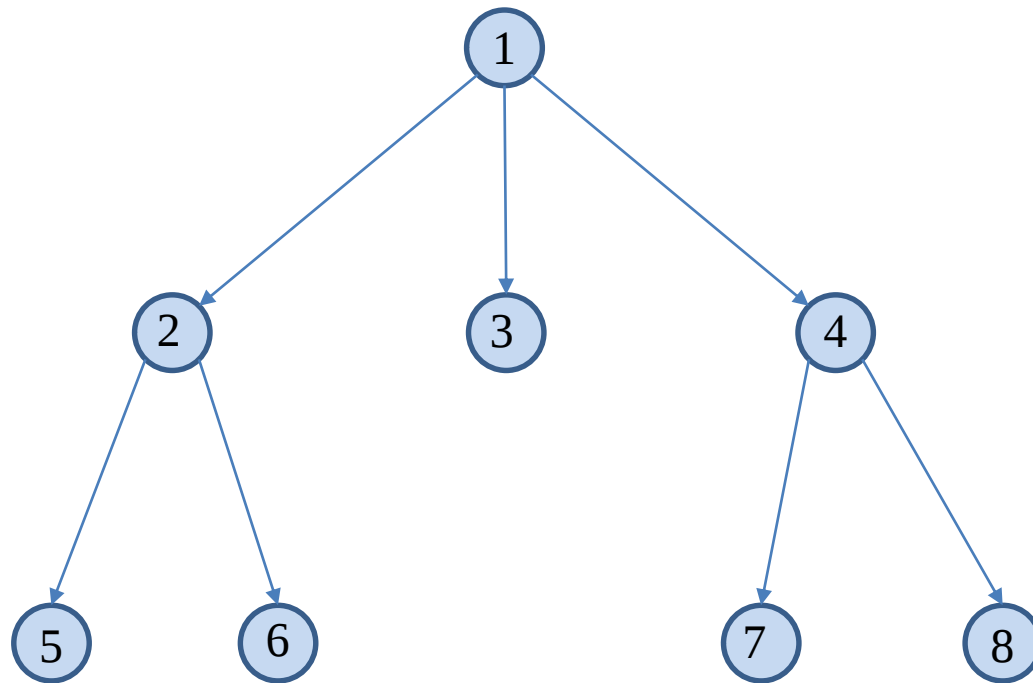
# Example of Recursive DFS

What is the order vertices are visited?



# Example

The vertices are visited in the order 1, 2, 5, 6, 3, 4, 7 and 8. This is different than the order we got when using a stack!



# Complexity of DFS

- DFS as implemented above (with adjacency lists) on a graph with  $e$  edges and  $n$  vertices has complexity  $O(n + e)$ .
- To see why observe that on no vertex is `traverse` called more than once, because as soon as we call `traverse` with parameter  $x$ , we mark  $x$  visited and we never call `traverse` on a vertex that has previously been marked as visited.
- Thus, the total time spent going down the adjacency lists is proportional to the lengths of those lists, that is  $O(e)$
- The initialization steps in `graph_dfs` have complexity  $O(n)$
- Thus, the total complexity is  $O(n + e)$



# Complexity of DFS

- If DFS is implemented using an adjacency matrix, then its complexity will be  $O(n^2)$ .
- If the graph is **dense (πυκνός)**, that is, it has close to  $O(n^2)$  edges the difference of the two implementations is minor as they would both run in  $O(n^2)$  time.
- If the graph is **sparse (αραιός)**, that is, it has close to  $O(n)$  edges, then the adjacency matrix approach would be much slower than the adjacency list approach.

# Complexity of BFS

- BFS with adjacency lists has the same complexity as DFS i.e.,  $O(n + e)$ .

# Readings

- T. A. Standish. *Data Structures , Algorithms and Software Principles in C*. Chapter 10
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- A. V. Aho, J. E. Hopcroft and J. D. Ullman. *Data Structures and Algorithms*. Chapters 6 and 7
- M. T. Goodrich, R. Tamassia and D. Mount. *Data Structures and Algorithms in C++*. 2nd edition. Chapter 13



