

# RUI ZHU

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## RESEARCH INTERESTS

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- **Inverse Rendering and Indoor Scene Understanding:** with a focus on physically-based material and lighting estimation of indoor scenes, for AR/VR applications (object insertion, scene editing, relighting, etc.).
- **Generative Modeling of Indoor Scenes:** generative methods for indoor scene generation and lighting estimation, and constructing large-scale datasets for photorealistic indoor inverse rendering.

## EDUCATION

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**Ph.D. Candidate in Computer Science, UC San Diego** La Jolla, CA, USA *Sep.2018 - Present*

- Thesis Proposal: **Bridging Semantic, Geometric and Physical Reasoning in Indoor 3D Scenes**
- Qualcomm Innovation Fellowship *2022 - 2023*
- Powell Fellow and Jacobs School of Engineering Fellowship at UCSD *2019 - 2021*

**M.S. in Robotics, Carnegie Mellon University** Pittsburgh, PA, USA *Aug.2015 - Aug.2017*

- Thesis: **Shape Prior Meets Geometry in Single and Multi-view Shape Reconstruction**

**B.Eng. in Information Engineering, Southeast University** Nanjing, Jiangsu, P.R.China *Aug.2011 - Jun.2015*

## PUBLICATIONS

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1. **Factorized Inverse Path Tracing for Efficient and Accurate Material-Lighting Estimation** Liwen Wu, **Rui Zhu** (equal contribution), Mustafa B. Yaldiz, Yinhao Zhu, Hong Cai, Janarбек Matai, Fatih Porikli, Tzu-Mao Li, Manmohan Chandraker, Ravi Ramamoorthi. *International Conference on Computer Vision (ICCV)*, 2023 (Oral)
2. **IRISformer: Dense Vision Transformers for Single-Image Inverse Rendering in Indoor Scenes** Rui Zhu, Zhengqin Li, Janarбек Matai, Fatih Porikli, Manmohan Chandraker. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2022 (Oral)
3. **Physically-based Editing of Indoor Scene Lighting from a Single Image** Zhengqin Li, Jia Shi, Sai Bi, **Rui Zhu**, Kalyan Sunkavalli, Milo Haan, Zexiang Xu, Ravi Ramamoorthi, Manmohan Chandraker. *European Conference on Computer Vision (ECCV)*, 2022
4. **PhotoScene: Physically-Based Material and Lighting Transfer for Indoor Scenes** anonymous. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2022 Yu-Ying Yeh, Zhengqin Li, Yannick Hold-Geoffroy, **Rui Zhu**, Zexiang Xu, Milo Haan, Kalyan Sunkavalli, Manmohan Chandraker.
5. **OpenRooms: An Open Framework for Photorealistic Indoor Scene Datasets** Zhengqin Li, Ting-Wei Yu, Shen Sang, Sarah Wang, Meng Song, Yuhan Liu, Yu-Ying Yeh, **Rui Zhu**, Nitesh Gundavarapu, Jia Shi, Sai Bi, Hong-Xing Yu, Zexiang Xu, Kalyan Sunkavalli, Milos Hasan, Ravi Ramamoorthi, Manmohan Chandraker. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2021 (Oral)
6. **Single View Metrology in the Wild** Rui Zhu, Xingyi Yang, Yannick Hold-Geoffroy, Federico Perazzi, Jonathan Eisenmann, Kalyan Sunkavalli, Manmohan Chandraker. *European Conference on Computer Vision (ECCV)*, 2020
7. **Deep Keypoint-Based Camera Pose Estimation with Geometric Constraints** Rui Zhu\*, You-Yi Jau\*, Hao Su, Manmohan Chandraker. *International Conference on Intelligent Robots and Systems (IROS)*, 2020

8. **ApolloCar3D: A Large 3D Car Instance Understanding Benchmark for Autonomous Driving** Xibin Song, Peng Wang, Dingfu Zhou, **Rui Zhu**, Yuchao Dai, Hao Su, Hongdong Li, Ruigang Yang. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2019
9. **Learning Depth from Monocular Videos using Direct Methods** Chaoyang Wang, Jose Miguel Buenaposada, **Rui Zhu**, Simon Lucey. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2018
10. **Object-Centric Photometric Bundle Adjustment with Deep Shape Prior** **Rui Zhu**, Chaoyang Wang, Chen-Hsuan Lin, Simon Lucey. *IEEE Winter Conference on Applications of Computer Vision (WACV)*, 2018
11. **Rethinking Reprojection: Closing the Loop for Pose-aware Shape Reconstruction from a Single Image** **Rui Zhu**, Hamed Kiani, Chaoyang Wang, Simon Lucey. *International Conference on Computer Vision (ICCV)*, 2017 (**Spotlight**)
12. **Semantic Photometric Bundle Adjustment on Natural Sequences** **Rui Zhu**, Chaoyang Wang, Ziyang Wang, Chen-Hsuan Lin, Simon Lucey. arXiv preprint, 2017
13. **The Conditional Lucas & Kanade Algorithm** Chen-Hsuan Lin, **Rui Zhu**, Simon Lucey. *European Conference on Computer Vision (ECCV)*, 2016
14. **Structure from Category: A Generic and Prior-less Approach** Chen Kong, **Rui Zhu**, Hamed Kiani, Simon Lucey. *International Conference on 3D Vision (3DV)*, 2016

## RESEARCH & INDUSTRY EXPERIENCE

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- **Rembrandt**, Remote *Sept. 2023 -*  
**Methods and large-scale datasets for generative indoor lighting estimation**  
 3D indoor lighting estimation and scene reconstruction from single/sparse-view input images of an indoor scene, via embedding geometry and physics into training diffusion models, using in-house generated large-scale synthetic datasets.
- **Qualcomm AI Research**, San Diego, USA *Jun. 2022 - Sep. 2022, Jun. 2023 - Sep. 2023*  
**Material, lighting and semantic estimation for multi-view indoor inverse rendering and scene editing**  
 Research Intern - Yinhao Zhu, Hebert Cai, Fatih Porikli, et al.
- **Nvidia Research**, Santa Clara, USA *Jun. 2021 - Sep. 2021*  
**Non-patch-based dense transformers for efficient scene representation**  
 Research Intern - Chao Liu, Ben Eckart, Jan Kautz
- **Microsoft Vision MR Team**, Seattle, WA, USA *Jun. 2020 - Sep. 2020*  
**Semantic stereo estimation**  
 Research Intern - Sudipta Sinha, Victor Fragoso
- **Adobe Research**, San Jose, CA, USA *Jun. 2019 - Sept. 2019*  
**Scene scale estimation from a single image in the wild**  
 Research Intern - Kalyan Sunkavalli, Yannick Hold-Geoffroy, Federico Perazzi
- **Baidu Research**, Sunnyvale, CA, USA *May. 2018 - Sept. 2018*  
**6DOF dense object reconstruction for autonomous driving applications**  
 Research Intern - Prof. Ruigang Wang & Dr. Peng Wang
- **Argo AI**, Pittsburgh, PA, USA *Feb. 2018 - May 2018*  
**3D object detection from front-view LiDAR data**  
 Research Engineer in Computer Vision - Prof. Deva Ramanan & Prof. Simon Lucey