

# FRIEDEM HAMANN

## Computer Vision Researcher

Berlin, Germany

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 friedhelmhamann.github.io/

 Google Scholar

PhD graduate in Computer Science, specializing in computer vision and machine learning. Expertise in robotic perception, tracking, generative vision models, and computational photography.

## Experience

### Doctoral Researcher - Robotic Perception, Technical University Berlin

Oct '21 - Sept '25

- Dissertation: "Dynamic Scene Understanding with Event Cameras"
- Built a transformer-based model and synthetic data pipeline for event-based point tracking, achieving +20% improvement over SOTA. ([CVPR'25 Highlight](#)).
- Formulated a self-supervised loss for non-linear trajectory estimation with event camera data, enabling large-scale training, improving over pure synthetic data training by 29% ([ECCV'24](#), [ICCV'25](#)).
- Constructed a system for low-power action detection and recognition for remote scenarios, doubling the time between manual battery changes of the remote-deployed system ([CVPR'24](#)).
- Developed a multi-modal video instance segmentation system, which included building a synchronized multi-camera system, implementation of a semi-automated annotation approach, and novel tracking methods combining filter-based approaches with transformer-based models ([ECCVW'24](#)).

### Research Assistant - Visual Computing, RWTH Aachen University

Oct '19 - Sept '21

- Built a generative model based on VQ-VAE's for video compression, including integration in H.266 test model.
- Created a hardware-in-the-loop system with an Nvidia Drive AGX and in-house simulation software (VeroSim) for end-to-end testing of autonomous driving algorithms, including integration of LiDAR and RGB data.

### Research Assistant - Camera Calibration, University Rostock

Jul '17 - Nov '18

- Developed camera calibration method for multi-camera systems in flow channels.

## Education

### Ph.D. Computer Vision, Technical University Berlin

Oct '21 - Sept '25

with Prof. Guillermo Gallego

### Research Visit, University of Pennsylvania, GRASP Lab

Sept '23 - Mar '24

with Prof. Kostas Daniilidis

### M.Sc. Computer Science, RWTH Aachen University

April '19 - Mar '21

GPA: 3.7/4.0 (German equivalent 1.4)

### B.Sc. Electrical Engineering, University Rostock

Oct '15 - Mar '19

GPA: 3.8/4.0 (German equivalent 1.3 )

## Selected Publications

Full and up to date publication list at: [Google Scholar](#)

- S. Guo, F. Hamann, and G. Gallego, "Unsupervised joint learning of optical flow and intensity with event cameras," *Int. Conf. Computer Vision (ICCV)*, 2025.
- F. Hamann, D. Gehrig, F. Febryanto, K. Daniilidis, and G. Gallego, "Etap: Event-based tracking of any point," in *IEEE Conf. Computer Vision and Pattern Recognition (CVPR)*, 2025.
- F. Hamann, S. Ghosh, I. J. Martinez, T. Hart, A. Kacelnik, and G. Gallego, "Low-power, continuous remote behavioral localization with event cameras," *IEEE Conf. Computer Vision and Pattern Recognition (CVPR)*, 2024.
- F. Hamann, Z. Wang, I. Asmanis, K. Chaney, G. Gallego, and K. Daniilidis, "Motion-prior contrast maximization for dense continuous-time motion estimation," *European Conference on Computer Vision (ECCV)*, 2024.
- S. Shiba, F. Hamann, Y. Aoki, and G. Gallego, "Event-based background-oriented schlieren," *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, 2023.